Data sheet
RM44D06_01
Issue 1, 19th December 2019

RM44/RM58 rotary magnetic encoder with AM4096

The RM44/RM58 is an encoder designed for integration onto electric motors or other devices for shaft position and rotational speed measurement.

The solid metal housing helps achieve the highest IP ratings, high EMC immunity, extended operating temperature range and the best possible shock and vibration resistance.

Output signals are provided in industry standard absolute, incremental, analogue sinusoidal and linear voltage formats. Available are resolutions of up to 12 bit absolute SSI and/or 4,096 counts per revolution incremental for 5 V or 24 V power supply.

With the provided magnet a system accuracy of ±0.5° is achievable. A range of magnetic actuators for easy integration onto or into the shaft is also offered for easy system integration.

Product range

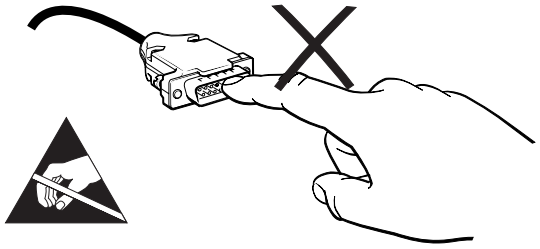
RM44/RM58I
Incremental with 80 to 2,048 pulses per revolution (320 to 4,096 counts per revolution with x 4 evaluation) and/or complementary analogue outputs with a single sine/cosine cycle per revolution.

RM44/RM58SC
Synchro serial interface (SSI) with 320 to 4,096 positions per revolution.

RM44/RM58SI
Synchro serial interface (SSI) with 320 to 4,096 positions per revolution and incremental with 80 to 2,048 pulses per revolution (320 to 4,096 counts per revolution with x 4 evaluation).

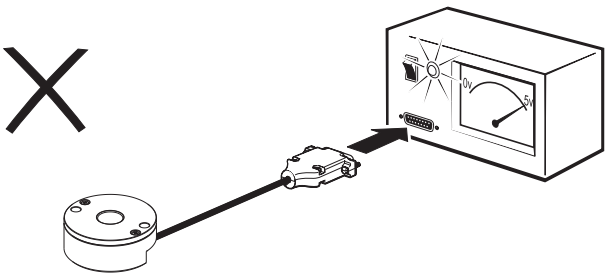
- **Easy to install – with self locating design**
- **Low cost for OEM integration**
- **Fully sealed to IP68**
- **High reliability from proven non-contact sensing technology**
- **CE compliant, including RoHS - see Declaration of conformity**

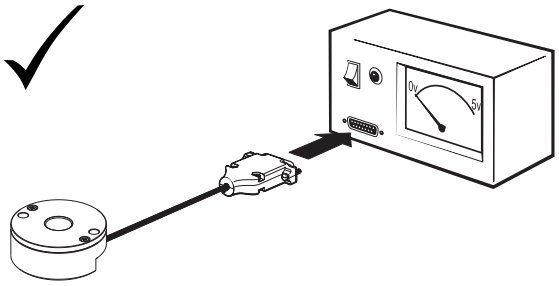
Storage and handling



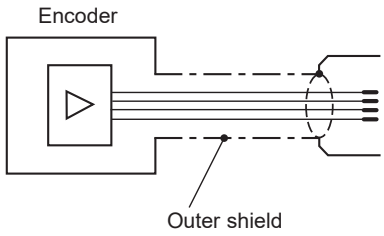
IMPORTANT: Power to RM44 encoders must be supplied from a DC SELV supply complying with the essential requirements of EN (IEC) 60950 or similar specification.

The RM44 series encoders have been designed to the relevant EMC standards, but must be correctly integrated to achieve EMC compliance. In particular, attention to shielding arrangements is critical.





Connections



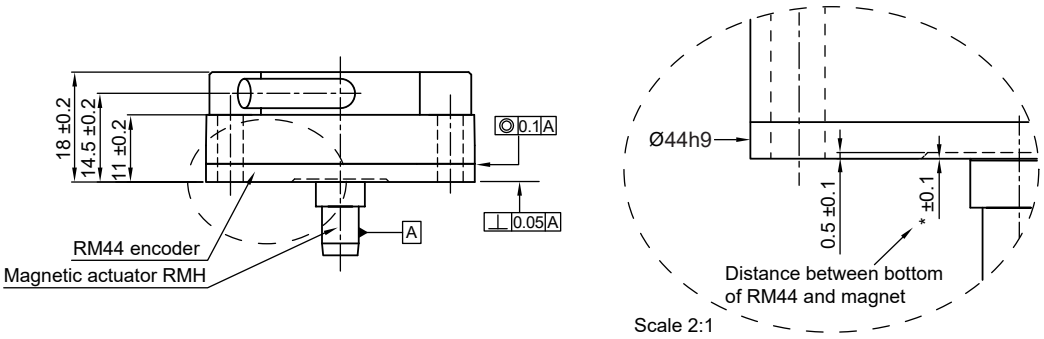
RM44/RM58IA		RM44/RM58IC		RM44/RM58IE		RM44/RM58SC		RM44/RM58SI	
Function	**Wire colour**	**Function**	**Wire colour**	**Function**	**Wire colour**	**Function**	**Wire colour**	**Function**	**Wire colour**
Shield - see connection diagram		Shield - see connection diagram		Shield - see connection diagram					
V_{dd}	Red	V_{dd}	Red	V_{dd}	Red	V_{dd}	Red	V_{dd}	Red
GND	Blue	GND	Blue	GND	Blue	GND	Blue	GND	Blue
A	Grey	A	Grey	A	Grey	Clock+	White	A	Grey
B	Green	B	Green	B	Green	Data+	Green	B	Green
Z	White	Z	White	Z	White	Clock–	Brown	Z	White
A–	Pink	A–	Pink			Data–	Yellow	A–	Pink
B–	Yellow	B–	Yellow					B–	Yellow
Z–	Brown	Z–	Brown					Z–	Brown
								Clock+	Black
								Data+	Grey/Pink
								Clock–	Violet
								Data–	Red/Blue

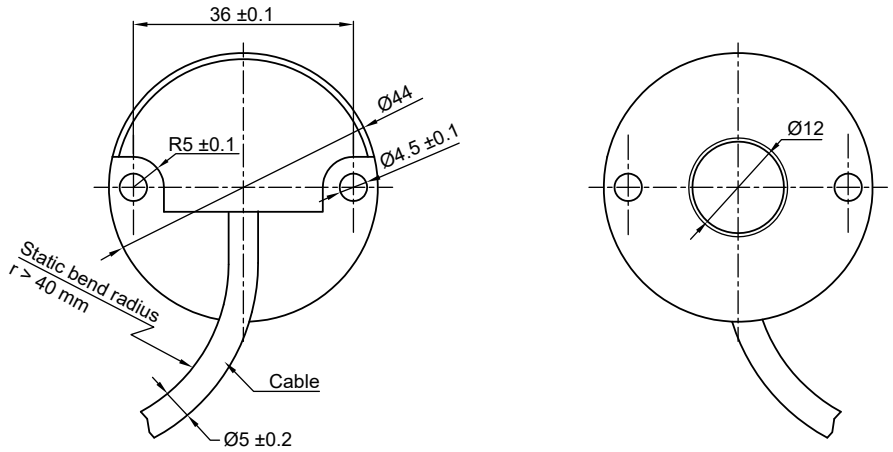
Operating and electrical specifications

EMC compliance	EN 61326
Cable	Outside diameter 5 mm
Mass	Encoder unit 1 m cable (no connector) IP64 112 g, IP68 129 g. Magnetic actuator <2 g
Environmental sealing	IP64 (IP68 optional) EN 60529

RM44 dimensions

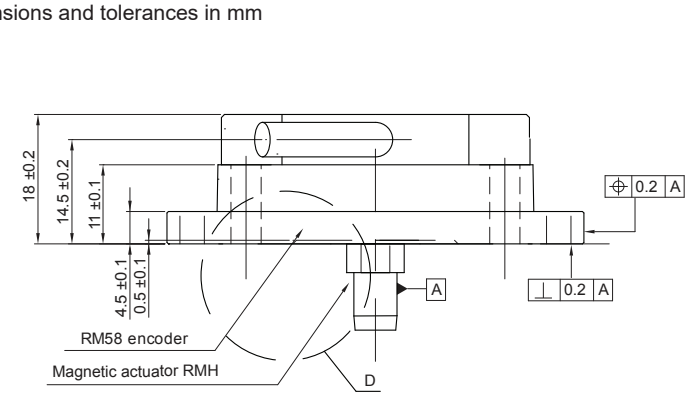
Dimensions and tolerances in mm

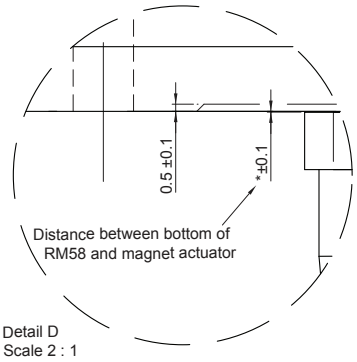


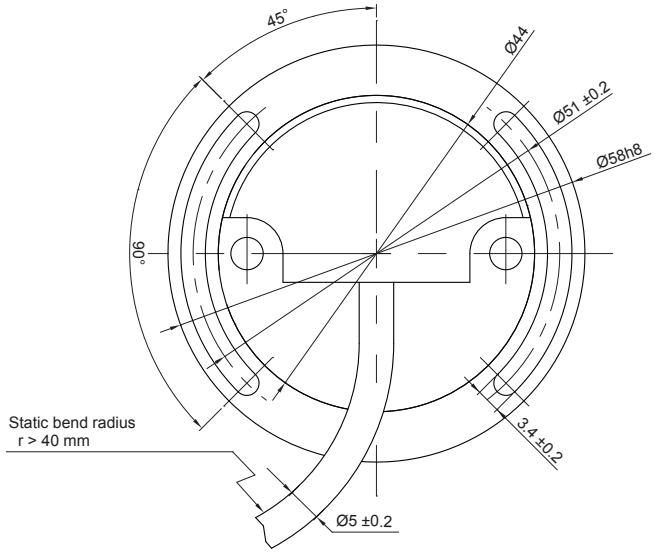


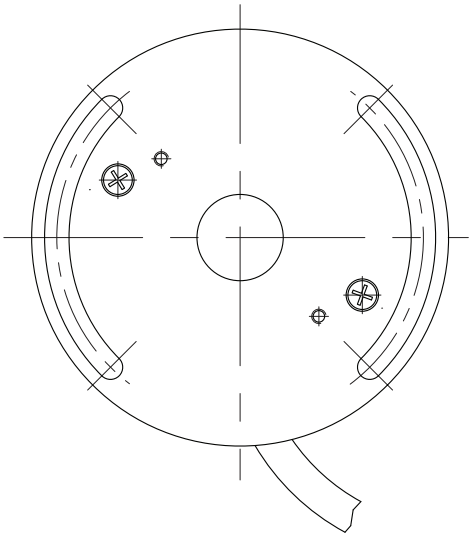
RM58 dimensions

Dimensions and tolerances in mm



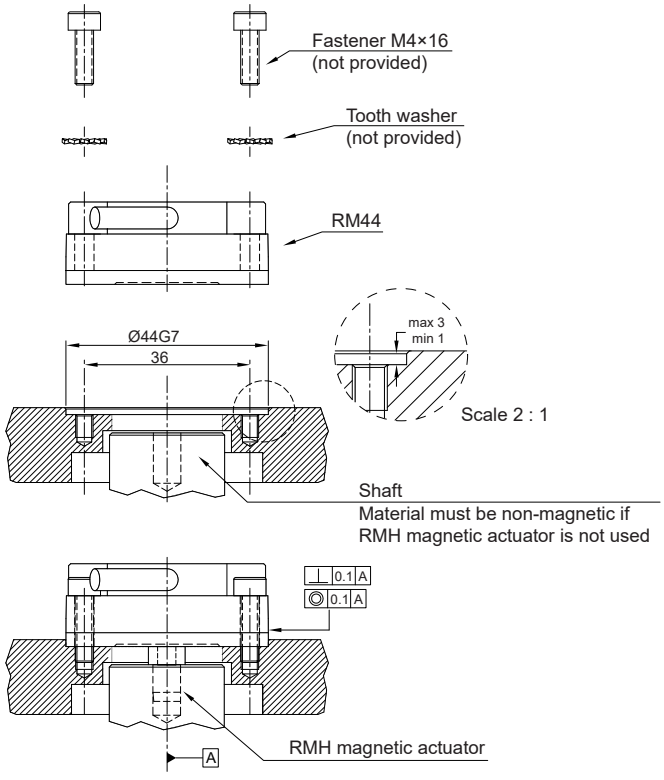


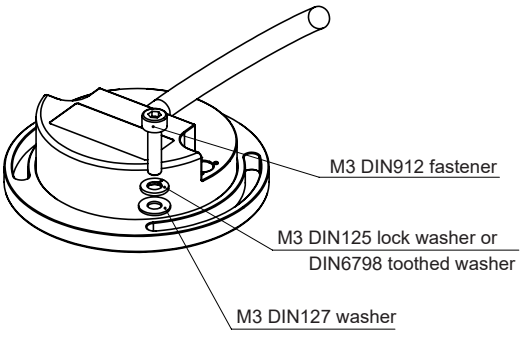




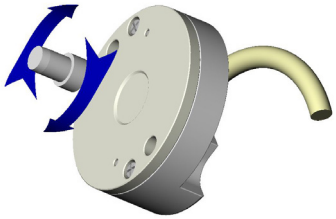
RM44 / RM58 installation drawing

Dimensions and tolerances in mm





Clockwise (CW) rotation of magnetic actuator

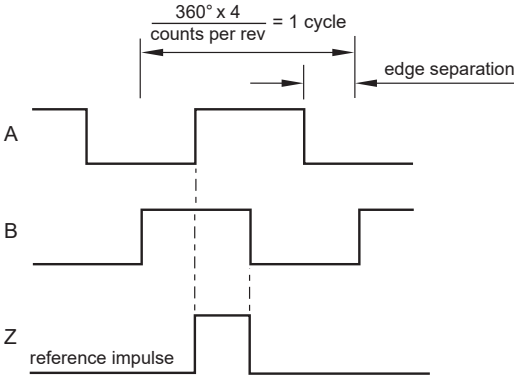


RM44IA / RM58IA – Incremental, Open Collector, NPN

Square wave output

Power supply	V_{dd} = 8 V to 26 V
Current consumption	50 mA
Output signals	A, B, Z, A–, B–, Z– (RS422)
Maximum output load	30 mA
Accuracy	Typ. ±0.5°
Hysteresis	0.18°
Resolution	32, 64, 128, 256, 512, 1,024, 2,048, 4,096 cpr
Maximum speed	60,000 rpm for resolutions up to 1,024 cpr 30,000 rpm for 2,048 and 4,096 cpr
Temperature Operating and storage	–40 °C to +125 °C (IP64) –40 °C to +85 °C (IP68)

Timing diagram



B leads A for clockwise rotation of magnet.

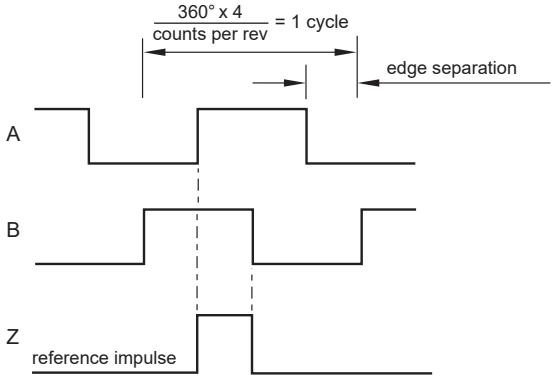
RM44IC / RM58IC– Incremental, RS422

Square wave differential line driver to RS422

Power supply	V_{dd} = 5 V ±5 %
Current consumption	Max. 35 mA
Output signals	A, B, Z, A–, B–, Z– (RS422)
Accuracy	±0.5°
Hysteresis	0.18°
Resolutions	32, 64, 128, 256, 512, 1,024, 2,048, 4,096 cpr
Maximum speed	60,000 rpm for resolutions up to 1,024 cpr 30,000 rpm for 2,048 and 4,096 cpr
Temperature Operating and storage	–40 °C to +125 °C (IP64) –40 °C to +85 °C (IP68)

Timing diagram

Complementary signals not shown



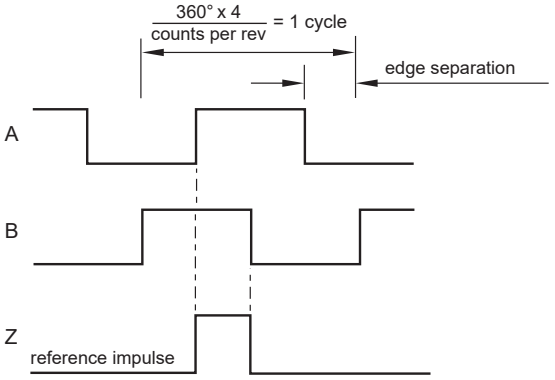
B leads A for clockwise rotation of magnet.

RM44IE / RM58IE – Incremental, Open Collector, NPN

Low cost alternative for ball bearing encoders

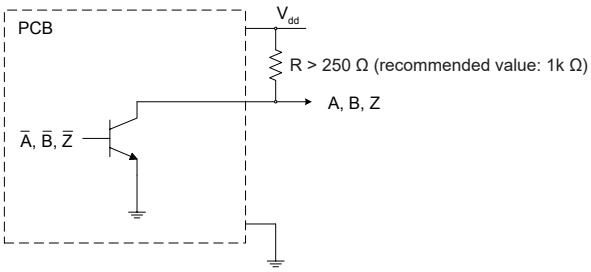
Power supply	V_{dd} = 5 V ±5 %
Current consumption	35 mA (not loaded)
Output signals	A, B, Z
Maximum output load	20 mA
Accuracy	Typ. ±0.5°
Hysteresis	0.18°
Resolutions	32, 64, 128, 256, 512, 1,024, 2,048, 4,096 cpr
Maximum speed	60,000 rpm for resolutions up to 1,024 cpr
	30,000 rpm for 2,048 and 4,096 cpr
Temperature Operating and storage	–40 °C to +125 °C (IP64) –40 °C to +85 °C (IP68)

Timing diagram



B leads A for clockwise rotation of magnet.

Recommended signal termination

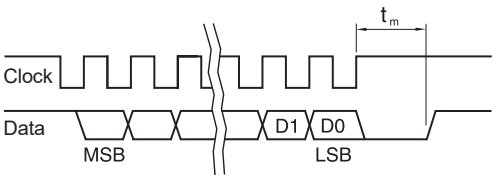


RM44SC / RM58SC – Absolute binary synchro-serial (SSI), RS422

Serial encoded absolute position measurement

Output code	Natural binary
Power supply	V_{dd} = 5 V ±5 %
Current consumption	Max. 35 mA
Data output	Serial data (RS422)
Data input	Clock (RS422)
Accuracy	Typ. ±0.5°
Hysteresis	0.18°
Resolutions	32, 64, 128, 256, 512, 1,024, 2,048, 4,096 cpr
Maximum speed	60,000 rpm for resolutions up to 1,024 cpr
	30,000 rpm for 2,048 and 4,096 cpr
Temperature Operating and storage	–40 °C to +125 °C (IP64) –40 °C to +85 °C (IP68)

Timing diagram



Clock ≤ 4 MHz 12.5 µs ≤ t_m ≤ 20 µs

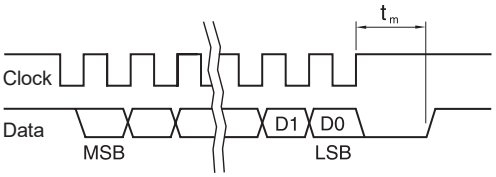
Position increases for clockwise rotation of magnet.

RM44SI / RM58SI – Absolute binary synchro-serial (SSI) + Incremental, RS422

Complex feedback device for absolute position at start up as well as during operation + incremental outputs.
Both the incremental and the SSI output always have the same fixed resolution.

Output code	Natural binary
Power supply	V_{dd} = 5 V ±5 %
Current consumption	Max. 35 mA
Incremental outputs	A, B, Z, A–, B–, Z– (RS422)
Data output	Serial data (RS422)
Data input	Clock (RS422)
Accuracy	Typ. ±0.5°
Hysteresis	0.18°
Resolutions	32, 64, 128, 256, 512, 1,024, 2,048, 4,096 cpr
Maximum speed	60,000 rpm for resolutions up to 1,024 cpr 30,000 rpm for 2,048 and 4,096 cpr
Temperature Operating and storage	–40 °C to +125 °C (IP64) –40 °C to +85 °C (IP68)

Timing diagram - SSI

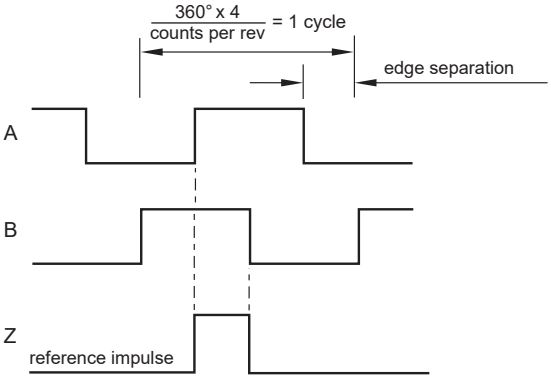


Clock ≤ 4 MHz 12.5 µs ≤ t_m ≤ 20.5 µs

Position increases for clockwise rotation of magnetic actuator.

Timing diagram - Incremental

Complementary signals not shown



B leads A for clockwise rotation of magnet.

Part numbering

Encoder system = Encoder body + Magnetic actuator or flange

RM44 encoder-sensor unit
eg. **RM44IC0013B10F2E10**

Magnetic actuator
eg **RMA06A3A00**

Flange
eg **RE58A10**

RM44 IC 00 12B 10 F 2 E 96

Series
RM44 - Ø44 mm body
RM58 - Ø58 mm body

Output type
IA - Incremental, Open Collector, NPN, 8 V to 26 V
IC - Incremental, RS422, 5 V
IE - Incremental, Open Collector, NPN, 5 V
SC - Absolute binary synchro-serial (SSI), RS422, 5 V
SI - SSI + Incremental, RS422, 5 V

Shaft size
00 - n/a

Resolution
Counts/positions per revolution:

05B - 32	**08B** - 256	**11B** - 2048
06B - 64	**09B** - 512	**12B** - 4096
07B - 128	**10B** - 1024	

Cable length
10 - 1.0 meter (or 10 meters if **1M** special requirement is chosen)

Connector options
F - Flying lead (no connector)

Body style and cable exit
2 - Cylindrical body, radial cable exit

Environment and material
E - IP64, die-cast body (Zinc alloy), standard EMC grade (standard)
F - IP68, die-cast body (Zinc alloy), standard EMC grade

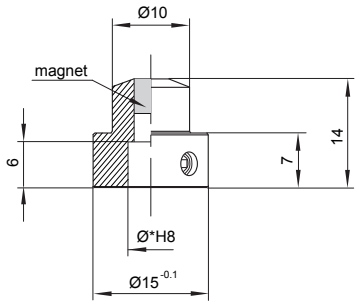
Special requirements
9M - With AM4096 and cable length in meters
96 - With AM4096 - up to 12 bit

NOTE: Not all combinations are valid.

Series	Output type	Shaft	Resolution	Cable length	Connector options	Special requirements
RM44 / RM58	IA	00	05B / 06B/ 07B / 08B / 09B / 10B / 11B / 12B	10	F	9M / 96
	IC					
	IE					
	SC					
	SI					

Magnetic actuators and magnets ordering information

Actuator for integration onto shaft



Shaft = Ø*h7
Fixing: Grub screw provided

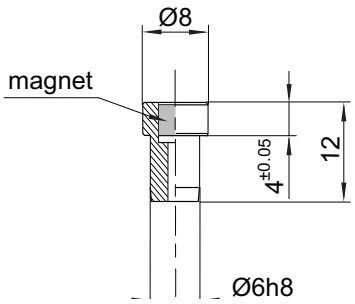
Part numbers:

For resolutions up to 9 bit absolute (512 cpr incremental)
RMA04A2A00 – Ø4 mm shaft **RMA10A2A00** – Ø10 mm shaft
RMA05A2A00 – Ø5 mm shaft **RMA19A2A00** – Ø3/16" shaft
RMA06A2A00 – Ø6 mm shaft **RMA25A2A00** – Ø1/4" shaft
RMA08A2A00 – Ø8 mm shaft **RMA37A2A00** – Ø3/8" shaft

For resolutions from 10 bit absolute (800 cpr incremental) and above
RMA04A3A00 – Ø4 mm shaft **RMA10A3A00** – Ø10 mm shaft
RMA05A3A00 – Ø5 mm shaft **RMA19A3A00** – Ø3/16" shaft
RMA06A3A00 – Ø6 mm shaft **RMA25A3A00** – Ø1/4" shaft
RMA08A3A00 – Ø8 mm shaft **RMA37A3A00** – Ø3/8" shaft

Actuator for integration into shaft


with N-pole marker



Hole = Ø6G7
Fixing: Glue (recommended – LOCTITE 648 or LOCTITE 2701)

Part numbers:

For resolutions up to 9 bit absolute (512 cpr incremental)
RMH06A2A00

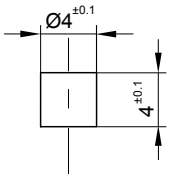
For resolutions from 10 bit absolute (800 cpr incremental) and above
RMH06A3A00

With N-pole marker scribed to a ± 5° accuracy:

For resolutions up to 9 bit absolute (512 cpr incremental)
RMH06A2A02

For resolutions from 10 bit absolute (800 cpr incremental) and above
RMH06A3A02

Magnet for direct recessing in non-ferrous shafts



Fixing: Glue (recommended – LOCTITE 648 or LOCTITE 2701)

Part numbers:

For resolutions up to 9 bit absolute (512 cpr incremental)
RMM44A2A00 (individually packed) – for sample quantities only
RMM44A2C00 (packed in tubes)

For resolutions from 10 bit absolute (800 cpr incremental) and above
RMM44A3A00 (individually packed) – for sample quantities only
RMM44A3C00 (packed in tubes)

RE58 flange part numbering

Refer to RE58 datasheet for further details.

Part numbers:

RE58A10 - Ø58 mm, 10 mm shaft

RE58B06 - Ø58 mm, 6 mm shaft

RE58C10 - Ø58 mm, 10 mm shaft

All RE58 flanges are supplied with required washer and M4 fasteners for RM44 encoder attachment.

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Document issues

Issue	Date	Page	Amendments done
1	19. 12. 2019	General	New document