

## **LA12** Absolute Magnetic Encoder System with Mitsubishi, Yaskawa and Fanuc Serial Communications

TRUE ABSOLUTE SYSTEM

LA12 is a true absolute magnetic encoder system designed for motion control applications as a position and velocity control loop feedback element. The encoder readhead is sealed to IP67 providing reliable and robust operation with high resolution.

ROBUST DESIGN

LOW LATENCY



### **Features and benefits**

- ► True absolute system
- ► Fanuc, Mitsubishi and Yaskawa serial communication protocols (Half-Duplex, RS-485)
- Suitable for highly dynamic control loops
- ▶ Robust design and great EMC compatibility
- ▶ IP67 sealing
- ► Speeds up to 7 m/s
- Axis lengths up to 16.3 m
- ► Resolutions up to ~0.244 μm











### **General information**

The LA12 encoder system provides true-absolute position information immediately after power-up over the two-wire communication protocol. The LA12 is extremely reliable due to the non-contact, wear-free measuring principle and the built-in safety algorithm.

The measuring standard is a magnetic scale that is magnetised with two tracks. The incremental track is magnetised with north/south 2 mm poles and the absolute track with a pseudo-random binary sequence.

The readhead consists of a Hall sensor array that reads the absolute track and an AMR sensor that reads the incremental track. The raw data is merged by the interpolator and the microcontroller unit. The position information is additionally processed in the FPGA, which enables low latency and short response time. Diagnostic information is available via the selected communication protocol and the multicolor status LED.

The readhead is connected to the outside world via a robust, highly flexible cable with various connection options. Due to the robust design of the readhead and the cable, the system ensures great electromagnetic compatibility (EMC).

### Choose your LA12 system

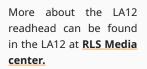
The LA12 readhead is compatible with the RLS absolute scale AS10 and solid absolute scale SAS10. You can select the length of the AS10 scale up to 16.3 m and SAS10 up to 1.35 m. To ensure safety and reliability, the AS10 scale can be optionally covered with a protective stainless steel foil or installed using TRS track system. The completely welded version of SAS10 magnetic scale is intended for harsh environments where contamination with industrial compounds is possible. The SAS10 scale also yields better accuracy compared to AS10 type of scale.

#### LA12 readhead

### AS10 magnetic scale

# TRS track system (AS10) SAS10 fully welded or exposed







More about the AS10 magnetic scales can be found in the ASD01 at **RLS Media center.** 



More about the TRS track system can be found in the ASD01 at RLS Media center.



More about the SAS10 fully welded scale can be found in the ASD01 at **RLS Media center.** 



## Storage and handling

Storage temperature



-20 °C to +85 °C

Operating temperature

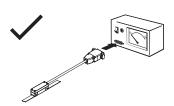


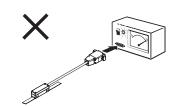
0 °C to +55 °C

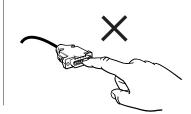
Humidity



High resistance to humidity



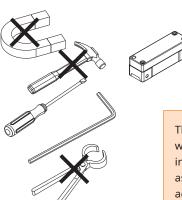






#### Readhead is ESD sensitive - handle with care.

Do not touch electronic circuit, wires or sensor area without proper ESD protection or outside of ESD controlled environment.



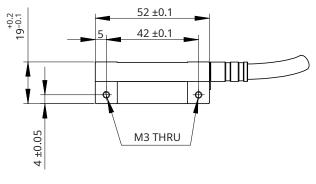
This encoder system is a high performance metrology product and should be handled with the same care as any other precision instrument. The use of industrial tools during installation or exposure to strong magnets such as a magnetic base is not recommended as it carries the risk of damaging parts of the system which as a result might not perform in accordance with specifications.

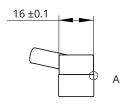
### **Packaging**

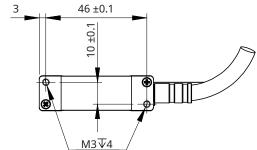
Each readhead is packed individually in an antistatic bag, according to ESD protection measures.

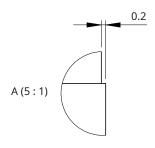
# **Dimensions drawing** Dimensions and tolerances are in mm.











General tolerances: ISO 2768 m K

3D model available for download at **RLS Media center.** 

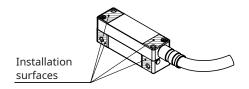


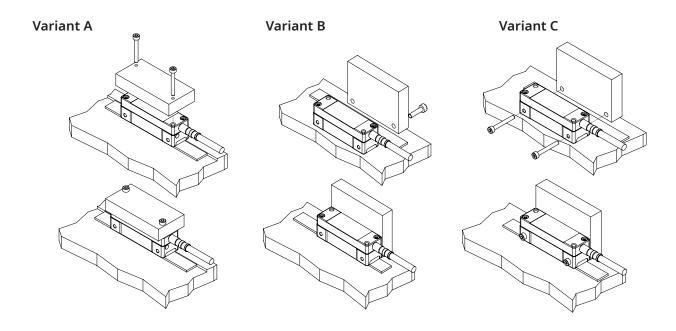
### **Installation instructions**

The readhead LED must be green at all measuring length positions. Otherwise, the installation will not be performed correctly. The 0.1 mm to 0.6 mm thick plastic spacer (shim) can be used to facilitate installation. For optimal installation, the recommended thickness of the shim is 0.2 mm.

After mounting the magnetic scale, place the plastic shim and the readhead on the magnetic scale. Make sure that the readhead, shim and magnetic scale are in full contact with each other. Ensure that the orientation and alignment of the readhead relative to the magnetic scale is as shown in the ASD01 at **RLS Media center**. The print on the scale can be used to determine the orientation.

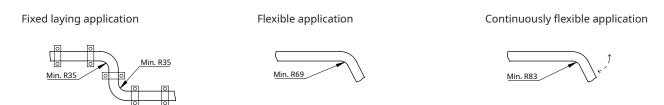
Improper mounting of the magnetic scale and readhead can impair the function of the magnetic encoder system and lead to total failure.





- The magnetic encoder system must be installed and mounted in strict compliance with the installation dimensions and tolerances given on **page 4** and in the ASD01 at **RLS Media center**. Contact between the readhead and magnetic scale must be avoided over the entire measuring range.
- The magnetic encoder system must be used in accordance with the specified degree of protection. The following factors must be taken into account: IP protection class, operating temperature, external magnetic field, mechanical load and EMC compatibility.
- The magnetic encoder system is sensitive to the external magnetic fields. The magnitude of the influence on the magnetic encoder system depends on the magnitude and direction of the external magnetic field. In particular, the rapidly changing stray magnetic fields affect the system and can alter its function. Magnetic field strength within 1 mT reduces the accuracy of the system. Field strengths greater than 1 mT will cause the system to malfunction and as a result the readhead will report an incorrect absolute position with the error status active. Magnetic field strengths greater than 25 mT will cause irreversible damage to the magnetic scale and will have to be replaced.

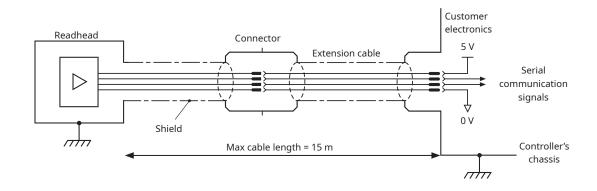
### Cable bending radius



The cable requires adequate strain relief to ensure integrity and avoid side forces that could damage the cable entry. The cable bending radius also applies to the connector side.

#### **Shield connection**

Figure below shows a recommended shield termination in order to ensure electromagnetic compatibility.

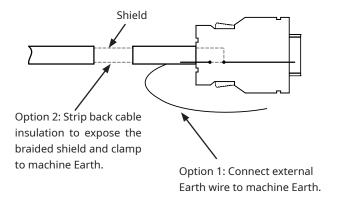


Housing of the encoder is galvanically connected with the housing of the connector. The encoder system must be correctly integrated to achieve EMC compliance. In particular, attention to shielding arrangements is essential.

#### Connecting the cable screen

The following arrangement should be applied to FANUC versions only.

The cable is supplied with the shield connected to pin 16 inside the connector, making the required connection to the FANUC equipment. The shield must also be connected to machine Earth, either by using the external Earth wire provided, or by cutting back the cable insulation to expose the shield and clamping that to machine Earth.





# **Technical specifications**

### System data

Pole length	2 mm					
Maximum measuring length	AS10: 16.3 m					
	SAS10: 1.288 n	n				
System accuracy	±20 μm/m to ±	±40 μm/m				
	For more infor	mation about accurac	cy of AS10 or SAS10 magnetic scale please refer to			
	ASD01 availab	le at <b>RLS Media cent</b> e	er.			
Hysteresis	<2 µm at 0.2 m	nm ride height				
Unidirectional repeatability	<1 µm	<1 μm				
Resolutions	Part number	Resolution	Max. speed			
Fanuc interface	8D0	0.25 μm	2 m/s			
Mitsubishi interface	1D0	2 μm	7 m/s			
	2D0	1 μm	7 m/s			
	11B	0.9765625 μm	7 m/s			
	12B	0.48828125 μm	4 m/s			
	13B	0.244140625 μm	2 m/s			
Yaskawa interface	11B	0.9765625 μm	7 m/s			
	12B	0.48828125 μm	4 m/s			
	13B	0.244140625 μm	2 m/s			
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### Electrical data

Power supply	From 4.75 V to 5.5 V (on the connector), reverse polarity protection			
Current consumption	<250 mA (at 5 V power supply and 15 m cable length, without load)			
Set-up time after power-on	<1 s (the encoder will start responding according to the communication protocol after			
	set-up time has passed)			
Position latency*	<1 µs			

 $<sup>\</sup>mbox{*Delay}$  caused by the sensor, interpolator and data processing.

#### Mechanical data

Material	Readhead: Aluminium (Eloxal - anodised)
Mass	86 g (readhead with 1 m cable, no connector)

### Cable

Cable type	Green colour, PUR high flex cable, UL AWM recognised, drag-chain compatible, tinned braided shield. RoHS approved.
Number of wires	6
Outer diameter	6.9 ±0.3 mm
Wires AWG	Green/Yellow/Blue/Pink 2 × 2 × 0.2 mm <sup>2</sup> + Red/Black 2 × 0.38 mm <sup>2</sup>
Cable bending radius*	Fixed installation: 35 mm, free movement: 69 mm, for continuous flexing: 83 mm
Mass	61 g/m
Torsion	Continuous torsion not allowed

<sup>\*</sup>Please see the chapter **Cable bending radius**.

### Environmental data

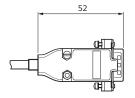
Temperature	Operating	0 °C to +55 °C		
	Storage	−20 °C to +85 °C		
Vibrations (55	Hz to 2000 Hz)	300 m/s² (IEC 60068-2-6:2007)		
Shocks (11 ms)	)	300 m/s² (IEC 60068-2-6:2007)		
Humidity		100 % (condensation permitted)		
EMC Immunity	/	EN IEC 61000-6-2:2019		
EMC Emission		EN IEC 61000-6-4:2019		
Environmental sealing		IP67 (according to IEC 60529:1992+A2:2013)		
External magnetic field		40 F 11-T		
during operation		<0.5 mT		



### **Electrical connections**

#### 10-way 20-way Fanuc M12 8-way 6-way Yaskawa Mitsubishi 9 pin D type plug (option V) (option W) (option Y) (option A) (option C) Wire **H** Function Signal colour 5 V 5 1 2 1 Red 9, 20 Power 0 V Black 9 2 12, 14 2 5, 8 2 5 MR Green 3 3 5 Serial communication MRR Yellow 3 6 4 6 7 6 Blue Reserved Pink 7 6 External shield, Shield Shield Shield Case Case Case Case pin 16

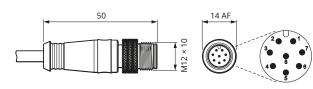
#### 9-way D-type connector



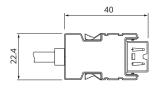




#### M12 8-way sealed connector (male type)



#### 10-way Mitsubishi connector (MOLEX 54599-1019)



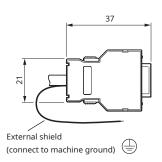


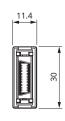


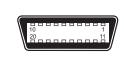
#### 6-way Yaskawa connector



#### 20-way Fanuc connector







### **Status indicator LED**

After installing the AS10 magnetic scale, the readhead can be easily adjusted on the machine using the LED setup indicator. The LED indicator shows the internal status of the encoder and is used for encoder installation and diagnostics.



Slow flashing LED indicates that power is being supplied to the encoder, but communication between the encoder and the controller has not yet been established. The error status has a higher priority than the warning status in the LED signaling. The LED signaling may be different from the encoder status signaled by the controller.

LED Status		Status	Description	
	Green	Normal operation	Position data is valid.	
•	Orange	Warning	Position data is valid. The internal temperature is near operational limits.	
•	Red	Error	<ul> <li>Position data is not valid. Possible causes:</li> <li>The distance between the readhead and the magnetic scale is too large.</li> <li>Signal lost.</li> <li>The readhead is out of alignment with the magnetic scale or the magnetic scale is demagnetised.</li> <li>Incorrect orientation of the readhead and the magnetic scale.</li> <li>The internal temperature is out of the operational limits.</li> <li>The encoder speed is out of operational limits.</li> </ul>	
••••	Fast red flashing	Error	Position data is not valid. Internal system error.	
•••	Slow red or green flashing	-	The communication has not been established.	
0	No light	No power supply	/	

During installation, the readhead must be moved for more than 10 mm above the magnetic scale to see the current encoder status on LED. The change from red to green color LED indicates a correctly installed encoder. After successful installation, perform a power off/on cycle.

The LED signal statuses listed in the table above do not indicate non-optimal installation of the readhead, such as accuracy outside the specified range.

If the readhead reports an error during operation as a result of incorrect decoding of absolute position on the magnetic scale, this indicates a serious issue. Serious issues are a wrong installation or damaged magnetic scale. To determine the root cause of the problem, please do the following:

- · Verify the installation that is in accordance with the LA12 specification (ride-height, lateral offsets and yaw/pitch/roll tolerances)
- If possible, check the error spot on the magnetic scale with the magnet viewer for the abnormal pattern in the magnetic code

Once the root cause is determined, please perform the power OFF-ON cycle of the readhead or move it for 10 mm over the scale.

The same behavior applies when the application in which the LA12 readhead is installed forces the readhead to leave the magnetic scale (no overlapping). In this case, when the readhead starts to overlap again from either side of the magnetic scale, the error disappears once the readhead travels 10 mm of valid position.



# **Output type**

#### Fanuc

Interface type	Alpha-I, Type-6, 2-wire (one pair transmission)		
Supported controllers*	30iB, 0i-D, F from its first version		
	<ul> <li>Series 15i, 16i, etc. 90B1 series/following versions from K(11)</li> </ul>		
	<ul> <li>Series 30i, etc. 90D0, 90E0 series/following versions from P(16)</li> </ul>		

### Mitsubishi

Interface type	2-wire RS-485 half-duplex		
Supported controllers*	MR-J4 (140J at the end of the PN)		
Compatible software version	From various C2 answerle		
of the controller/servo	rom version C3 onwards		

### Yaskawa

nterface type Yaskawa, 2-wire (one pair transmission)	
Supported controllers*	Version 0021 onwards of Sigma-LINK with Sigma-7

 $*Not all \, controllers \, are \, listed. \, Please \, contact \, the \, controller \, manufacturer \, to \, confirm \, product \, compatibility.$ 

### **Part numbering**

LA12 MS 13B Α Α 50D C 00 Α **Communication interface** FA - Fanuc interface MS - Mitsubishi interface YA - Yaskawa interface **Communication interface variant** A - Two-wire interface (half-duplex RS485) Resolution For **FA**: **8D0** - 0.25 μm For MS: **13B** - 0.244140625 μm **12B** - 0.48828125 μm **11B** -  $0.9765625 \, \mu m$ **2D0** - 1 μm **1D0** - 2 μm For YA: **13B** - 0.244140625 μm **12B** - 0.48828125 μm **11B** - 0.9765625 μm Minimum edge separation A - N/A **Power supply** A - 5 V (regardless of cable length up to 15 m) Cable length **10D** - 1 m **70D** - 7 m **20D** - 2 m 10M - 10 m **30D** - 3 m **12M** - 12 m Maximum cable length is 15 m. If extension **40D** - 4 m **15M** - 15 m cable is used, the readhead cable length + **50D** - 5 m extension cable length must not exceed 15 m. **Connector options** A - 9 pin D type plug **C** - 10-way Mitsubishi (Molex 54599-1019) **F** - Flying leads (no connector) V - 20-way Fanuc connector W - 8-way M12 (sealed) connector Y - 6-way Yaskawa **Special requirements** 

For the extension cable (Female M12 to dedicated connector), please contact RLS.

00 - No special requirements (standard)



### Table of available combinations

Series	Communication interface	Comm interface variant	Resolution	Minimum edge separation	Power supply	Cable length	Connector option	Special requirements
	FA		8D0			10D / 20D /	A/F/V/W	
LA12	MS	A	13B / 12B / 11B / 2D0 / 1D0	А	Α	30D / 40D / 50D / 70D / 10M / 12M /	A/C/F/W	00
	YA		13B / 12B / 11B			15M	A/F/W/Y	



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#### **Document issues**

Date	Page	Description
21. 9. 2021	General	New document
4. 2. 2022	General	AS removed
1. 4. 2022	11	Mitsubishi supported controllers amended

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