

RoLin™ miniature packaged incremental magnetic encoder sensor system



RoLin[™] is a component level encoder consisting of a RLM readhead and a magnetic scale or ring. It has been designed for embedded motion control applications as a position control loop element.

The information carrier is a periodically magnetised scale with a pole length of 2 mm. Radial or axial reading of the ring is possible.

State of the art position sensing ensures highly repeatable position measurement under wide installation tolerances and temperature ranges.

Position information is output in incremental quadrature and parallel, SSI or BiSS format with the option of a periodic reference mark (every pole). When SSI or BiSS

communication protocol is selected the value of internal period counter (1 pole = 1 period) can be output. 8 bit, 12 bit or 24 bit counter lengths can be selected. Optionally, period counter can be reset when traversing the reference mark (if selected).

Maximum speed depends on the chosen resolution and minimum edge separation time; e.g. for linear applications to 7 m/s at 1 µm and to 75 m/s at 10 µm. For more information about maximum speed in rotary and linear applications download MR or MS datasheet from RLS media

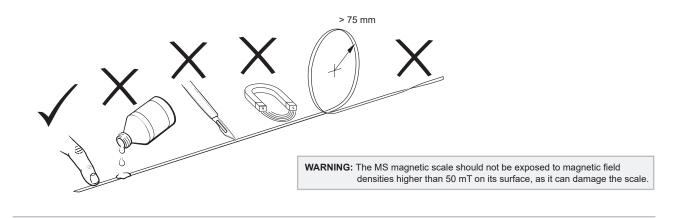
A self-diagnosis feature enables the sub-system to diagnose potential failures of the encoder which are signalled on the Error line using a PWM formatted code.

- Incremental ABZ, TTL or RS422 logic level
- SSI or BiSS, TTL logic level
- High speed operation
- Bidirectional reference mark
- High reliability from proven noncontact sensing technology
- Pin / Flex cable options
- Self-diagnosis feature
- CE compliant, including RoHS see <u>Declaration of conformity</u>

Readhead selection guide

	RLM with pins	RLM with flex cable	RLM with RS422 flex cable		
			Dames Control		
Fixing of readhead	By soldering	Mounting bracket	Mounting bracket		
Connection to system PCB	Direct soldering to PCB	With flex cable and zif connector	With flex cable and zif connector		
Available flex cable output lengths	-	75 mm	136 mm		
Overall distance to subsequent device	Distance depends on loading characteristics and edge separation time; generally: <300 mm	Distance depends on loading characteristics and edge separation time; generally: <300 mm	>50 m (with FPC and extesion cables)		
Output type	SSI, BiSS-C and Incremental, no line driver (A, B, Z)	SSI, BiSS-C and Incremental, no line driver (A, B, Z)	Incremental, RS422 line driver (A, B, Z, A-, B-, Z-)		
Error signal	Available	Available	Not available		
ESD susceptibility of all pins	$\pm 2 \text{ kV}$ (HBM 100 pF, discharge through 1.5 k Ω)	±2 kV (HBM 100 pF, discharge through 1.5 k Ω)	±2 kV (HBM 100 pF, discharge through 1.5 kΩ)		

Storage and handling















* Use of alcohol for cleaning is considered safe, however, it is not allowed to immerse the scale in alcohol.



For radial and axial ring storage and handling download MR data sheet from RLS media center.



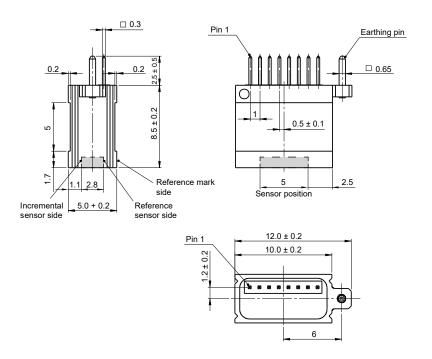
RLM readhead with pins for direct soldering to PCB

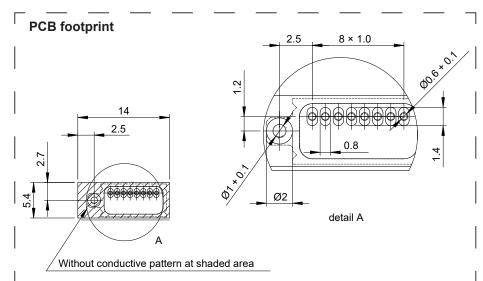
Dimensions and tolerances are in mm.



Pinout

Pin	Signal	Function
1	SLO	Output
2	MA	Input
3	Error	Output
4	V _{dd} (+5 V)	Power
5	GND (0 V)	Power
6	А	Output
7	Z	Output
8	В	Output





Data sheet RLMD01_09

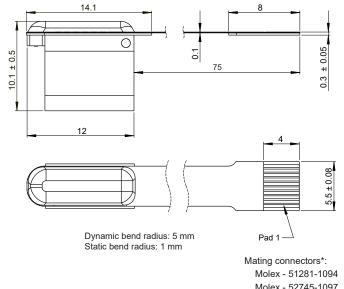
RLM readhead with flex cable

Dimensions and tolerances are in mm.



Connections

Pad	Signal	Function
1	-	Case
2	SLO	Output
3	MA	Input
4	Error	Output
5	V _{dd} (+5 V)	Power
6	GND (0 V)	Power
7	А	Output
8	Z	Output
9	В	Output
10	-	Case



Molex - 51281-1094 Molex - 52745-1097 Molex - 52746-1071 JST - 10FLH-SM1-TB

JST - 10FLH-RSM1-TB

* Not provided.

RLM readhead with RS422 flex cable

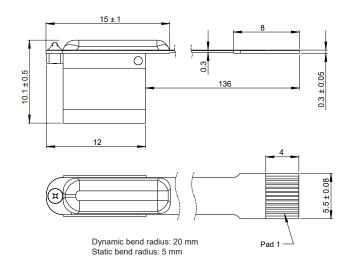
Dimensions and tolerances are in mm.



Connections

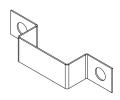
Pad	Signal	Function
1	-	Case
2	Α	Output
3	A-	Output
4	B-	Output
5	V _{dd} (+5 V)	Power
6	GND (0 V)	Power
7	В	Output
8	Z-	Output
9	Z	Output
10	-	Case

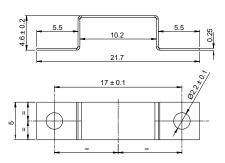
Note: Error signal not output



Mounting bracket dimensions

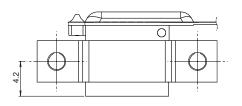
Dimensions and tolerances are in mm.





Position of installation holes

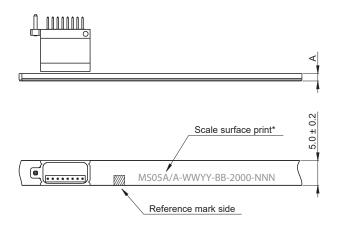
Recommended use of M2 screws with washers.





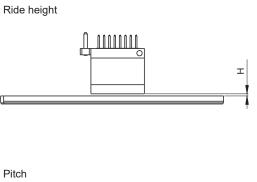
Installation tolerances

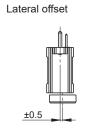
Dimensions and tolerances are in mm.

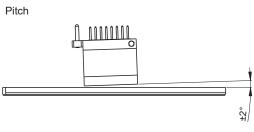


	Magnetic scale thickness (A)	Ride height (H)
With back-adhesion	1.5 ± 0.15	0.1–0.8
tape (option A) With back-adhesion		
tape, with cover foil (option B)	1.6 ± 0.15	0.1–0.7
No back-adhesion tape (option I)	1.3 ± 0.15	0.1–0.8
No back-adhesion tape, with cover foil (option N)	1.4 ± 0.15	0.1–0.7

^{*} For scale surface print description refer to MS01 datasheet.

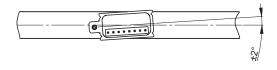








Yaw



For radial and axial ring installation tolerances download MR datasheet from $\underline{\mathsf{RLS}}$ media center.

Technical specifications

System data	
Maximum length for MS05 scale	50 m
Pole length	2 mm
System accuracy	±40 μm
Linear expansion coefficient for MS scale	~ 17 × 10 ⁻⁶ /K
Repeatability	Better than unit of resolution for movement in the same direction
Hysteresis	< 3 µm up to 0.2 mm ride height
Hand soldering (for pin variant only)	T _{max} 260 °C; t _{max} 5 s

Available resolutions and maximum speed for linear applications:

Part numbering	Resolution (µm)	Counts / 2 mm				Ma	ximum spe (m/s)	ed			
13B	≈ 0.244	8,192	1.82	0.91	0.23	0.11	0.06	0.03	0.02	0.01	0.01
12B	≈ 0.488	4,096	3.65	1.82	0.46	0.23	0.12	0.06	0.05	0.02	0.01
11B	≈ 0.976	2,048	7.30	3.65	0.91	0.46	0.24	0.12	0.10	0.05	0.02
2D0	1	2,000	7.47	3.73	0.93	0.47	0.24	0.12	0.10	0.05	0.02
1D6	1.25	1,600	9.33	4.67	1.17	0.58	0.30	0.16	0.12	0.06	0.03
10B	≈ 1.953	1,024	14.58	7.30	1.82	0.91	0.48	0.24	0.19	0.10	0.05
1D0	2	1,000	14.93	7.47	1.87	0.93	0.49	0.25	0.20	0.10	0.05
D80	2.5	800	18.67	9.33	2.34	1.17	0.61	0.31	0.25	0.12	0.06
09B	≈ 3.906	512	29.17	14.58	3.65	1.82	0.95	0.49	0.38	0.19	0.10
D50	4	500	29.87	14.93	3.73	1.87	0.97	0.50	0.39	0.20	0.10
D40	5	400	37.33	18.67	4.67	2.34	1.22	0.62	0.49	0.25	0.12
D32	6.25	320	46.67	23.33	5.84	2.91	1.52	0.78	0.61	0.31	0.16
08B	≈ 7.812	256	58.34	29.17	7.30	3.65	1.90	0.97	0.77	0.39	0.19
D20	10	200	74.67	37.33	9.33	4.67	2.43	1.24	0.98	0.50	0.2
D16	12.5	160	80.00	46.87	11.75	5.81	3.06	1.53	1.23	0.61	0.3
07B	15.625	128	80.00	58.34	14.58	7.30	3.81	1.94	1.53	0.77	0.39
D10	20	100	80.00	75.00	18.80	9.30	4.90	2.45	1.96	0.98	0.49
D08	25	80	80.00	80.00	23.50	11.63	6.13	3.06	2.45	1.23	0.6
06B	31.25	64	80.00	80.00	29.17	14.58	7.62	3.89	3.07	1.55	0.78
D04	50	40	80.00	80.00	47.00	23.25	12.25	6.13	4.90	2.45	1.23
05B	62.5	32	80.00	80.00	58.34	29.17	15.22	7.78	6.14	3.10	1.56
04B	125	16	n/a	80.00	80.00	58.34	30.43	15.56	12.28	6.19	3.1
03B	250	8	n/a	n/a	80.00	80.00	60.86	31.11	24.56	12.39	6.23
Minimum edge separation (μs)		0.07	0.12	0.50	1	2	4	5	10	20	
Max	kimum count fre	quency (MHz)	15	8	2	1	0.5	0.25	0.2	0.1	0.0
	Pa	art numbering	K	Α	В	С	D	E	F	G	Н

For rotary maximum speed table refer to MR datasheet from RLS media center.

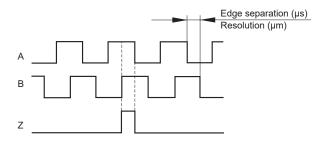
Mechanical data		
Readhead housing material	ZnAl4Cu1 - zamak 5	
Mass	RLM readhead 1.4 g (without flex), 1.6 g (with flex); magnetic scale MS05 30 g/m; for radial and axial rings downlad MR datasheet from RLS media center	
Environmental		
Temperature	Operating With flex cable: -20 °C to +85 °C	
	Without flex cable: -40 °C to +85 °C	
	Storage —40 °C to +85 °C	
Vibrations (55 Hz to 2000 Hz)	300 m/s ² (IEC 60068-2-6)	
Shocks (11 ms)	300 m/s ² (IEC 60068-2-27)	
RoHS	Compliant with EU Directive 2002/95/EC	



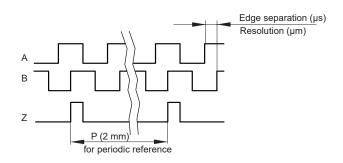
RLM2DE - BiSS-C + Incremental, no line driver

Power supply (voltage on readhead)	4.75 V to 5.5 V Reverse polarity protection
Current consumption	< 25 mA (without load)
Output signals	A, B, Z, Error, SLO
Saturation voltage hi (I = -4 mA)	$V_{dd} - 0.4 V$
Saturation voltage lo (I = 4 mA)	0.4 V
Rise and fall time (c _c = 50 pF)	60 ns
Input signals	MA
Threshold voltage hi	2 V
Threshold voltage lo	0.8 V
Permissible MA clock frequency	8 MHz
Reference signal	1 or more square-wave pulse Z
Timeout (Tto)	1.5 µs

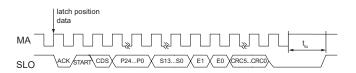
Timing diagram – Incremental, unique reference mark



Timing diagram - Incremental, periodic reference mark



Timing diagram - BiSS-C



Data	Length	Description
P24 – P0	0 to 24 bit	Period counter value (length depends on the settings chosen)*
S12 – S0	3 to 13 bit	Position inside the period (length depends on the resolution)
E1 – E0	2 bit	Error data
CRC5 – CRC0	5 to 6 bit	Cyclic redundancy check data; polynomial 0 × 25; inverted bit output

* Optionally, period counter can be reset at the reference mark (options E, F and G - see part numbering on page 10).

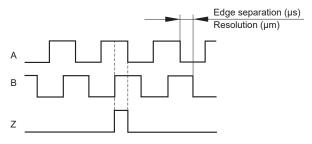
Error	E0	E1
No error	1	1
Amplitude error	0	1
Too high velocity	1	0
Undervoltage; Configuration; System error	0	0

For more information on BiSS-C protocol please visit their $\underline{\text{webpage}}.$

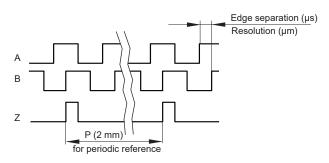
RLM2HD - Incremental, no line driver

4.75 V to 5.5 V Reverse polarity protection
<25 mA (without load)
A, B, Z
$V_{dd} - 0.4 V$
0.4 V
60 ns
1 or more square-wave pulse Z

Timing diagram - Incremental, unique reference mark



Timing diagram - Incremental, periodic reference mark

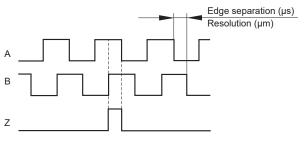


RLM2IC - Incremental, RS422

Power supply (voltage on readhead)	4.75 V to 5.5 V Reverse polarity protection
Current consumption	<30 mA (without load)
Output signals	A, B, Z, A-, B-, Z-
High level output voltage (I _{OH} = -20 mA)	>2.4 V
Low level output voltage (I _{oL} = 20 mA)	<0.4 V
Rise and fall time $(c_c = 50 \text{ pF})$	<10 ns
Reference signal	1 or more square-wave pulse Z and its inverted pulse Z-

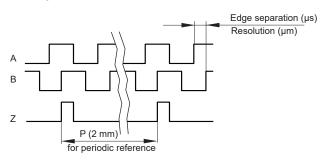
Timing diagram – Incremental, unique reference mark

Inverted signals are not shown



Timing diagram – Incremental, periodic reference mark

Inverted signals are not shown

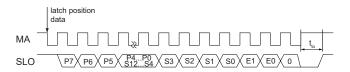




RLM2SJ - SSI + Incremental, no line driver

Power supply (voltage on readhead)	4.75 V to 5.5 V Reverse polarity protection
Current consumption	<25 mA (without load)
Output signals	A, B, Z, Error, SLO
Saturation voltage hi (I = -4 mA)	$V_{dd} - 0.4 V$
Saturation voltage lo (I = 4 mA)	0.4 V
Rise and fall time (c _c = 50 pF)	60 ns
Input signals	MA
Threshold voltage hi	2 V
Threshold voltage lo	0.8 V
Permissible MA clock frequency	4 MHz
Reference signal	1 or more square-wave pulse Z
Timeout (Tto)	20 μs

Timing diagram - SSI



Error	E0	E1
No error	1	1
Amplitude error	0	1
Too high velocity	1	0
Undervoltage; Configuration; System error	0	0

Data	Description			
P0 - P7	Period counter value (length depends on the settings chosen)*			
S0 - S13	Position inside the period (length depends on the resolution)			
E1 - E0	Error data			

^{*} Optionally, period counter can be reset at the reference mark (options E, F and G - see part numbering on page 10).

Error output

To enable the successful diagnosis of faults, different types of errors are signalled on the Error line using a PWM formatted code as detailed below. In the case of amplitude or frequency failure the PWM cycle frequency is approximately 16.5 Hz (cycle duration: 60.7 ms).

Failure mode	Error output	Possible cause of failure
No error	High	Ride height too high
Amplitude error	Low: 75 % High: 25 %	Readhead removed from scale / ring Demagnetisation of magnetic scale / ring
Frequency error	Low: 50 % High: 50 %	Speed too high
Undervoltage	Low	Power supply low

If an error in amplitude occurs, the conversion process is terminated and the incremental output signals are halted. An error in amplitude rules out the possibility of an error in frequency.

Error output is an open collector type with built in pull up resistor. It can be used in "wired-or" configuration with other error signals in the system.

Reference mark options

Option A:: With reference sensor

Magnetic scale or ring should be ordered with reference mark. If required, the cover foil can be installed over the reference mark.

Option B: No reference sensor

Option C: Periodic reference mark as per scale pitch (every 2 mm)

Reference periods correspond to pole length of magnetisation. Magnetic scale or ring should be ordered with <u>no</u> reference mark

Interpolation factor (resolution)

Formula for linear application resolution

Resolution (
$$\mu$$
m) = $\frac{2000}{Interpolation}$

Formula for rotary application resolution

Resolution (ppr) =
$$\frac{\text{cpr}}{4}$$

Resolution (cpr) = Pole number × Interpolation

For radial and axial ring resolution download MR datasheet from RLS media center.

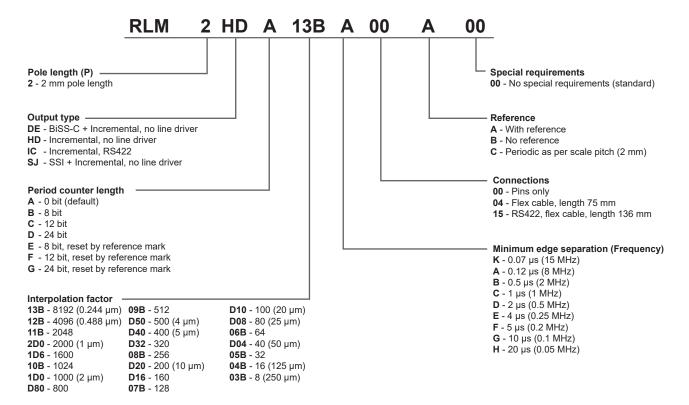
Data sheet

RLMD01_09

Readhead part numbering



RLM readhead eg. RLM2HDA13BA00A00 Magnetic scale / ring eg. MS05BM100AM010 for scale / MR047B040A076B00 for ring RoLin™ system

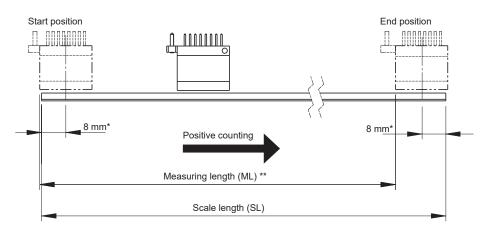


Series	Output type	Period counter length	Interpolation factor	Minimum edge separation	Connections	Reference	Special Requirements
	IC	- А	xxx*	K/A/B/C/D/E /F/G/H	15	A/B/C	00
			04B	A/B/C/D/E/F /G/H		B/C	
			03B	B/C/D/E/F/ G/H			
	HD		xxx*	K/A/B/C/D/E /F/G/H	00 / 04 / 15	A/B/C	
RLM2			04B	A/B/C/D/E/F /G/H		B/C	
			03B	B/C/D/E/F/ G/H			
	DE/SJ /	A/B/C/D/E /F/G	xxx*	K/A/B/C/D/E /F/G/H		A/B/C	
			04B	A/B/C/D/E/F /G/H		B/C	
			03B	B/C/D/E/F/ G/H			

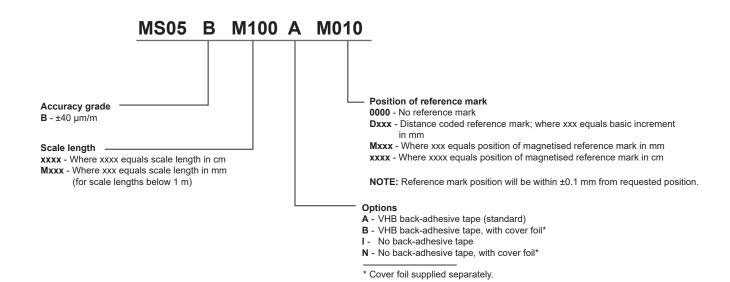
For radial and axial ring part numbering refer to MR datasheet from RLS media center.



Magnetic scale part numbering



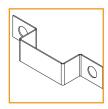
- * Minimum distance of reference mark from left edge is 8 mm.
- ** Beginning of measuring length from elasto-ferrite layer edge is 0 mm. *ML* = *SL* - 10 mm



Cover foil part numbering



Accessories part numbering



Mounting bracket

RLMMB01



USB encoder interface

E201



Connector adapters FFC to DB9 (connect to E201):

RLACC001 for RLM2IC

RLACC002 for RLM2HD

RLACC003 for RLM2DE and RLM2SJ

RLACC004 for RLM2IC



Magnet viewer

MM0001



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Document issues

Issue	Date	Page	Corrections made			
5	25. 11. 2014	2	Updated installation drawing dimension tolerance			
		3	Magnetic scale thickness information updated			
		4	Ring dimension tolerances updated; installation note added			
		7	Edge separation and reference notes added			
		8	Part numbering Options added			
6	22. 12. 2014	1, 12	Period counter options added and explained			
7	14. 1. 2015	7	76 pole ring resolutions corrected			
8	18. 9. 2017	1	Ring reference and RoHS added			
		2	Storage added			
		6	Technical specifications amended			
		7, 8	Output description added			
		10, 11, 12, 13	Readhead, magnetic scale and accessories part numbering amended			
9	14. 2. 2020	5	Installation drawing amended			
		6	Temperature range amended			
			Maximum speed table amended			
		7, 8, 9	Current consumption amended			

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