

RE22 rotary magnetic shaft encoder



The RE22 is a compact, high-speed rotary magnetic encoder designed for use in harsh environments. The traditional design allows for easy integration to existing machines.

A magnet is mounted to the shaft within the encoder body. Rotation of this magnet is sensed by a custom encoder chip within the body, and processed to give the required output format.

The encoder chip processes the signals received to provide resolutions of up to 13 bit (8,192 positions per revolution) with high operational speeds. Output signals are provided in industry standard absolute, incremental, analogue or linear formats.

The compact encoder body is just 22 mm in diameter and provides dirt immunity up to IP53.

The RE22 can be used in a wide range of applications including marine, medical, print, converting, industrial automation, metal working and instrumentation.

Product range RE22AC

Analogue with a single sine/cosine cycle per revolution

RE22BC

Complementary analogue outputs with a single sine/cosine cycle per revolution

RE22DC

BiSS C interface with up to 8,192 positions per revolution and optional revolution counter

RE22IC

Incremental with 80 to 2,048 pulses per revolution (320 to 8,192 counts per revolution with x 4 evaluation)

RE22SC

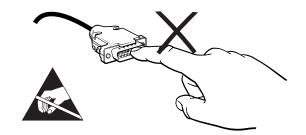
Synchro serial interface (SSI) with 320 to 8,192 positions per revolution

RF22\/\

Linear voltage output in a range of variants

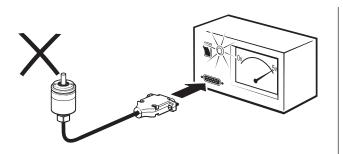
- High speed operation to 30,000 rpm
- Compact 22 mm diameter body
- Absolute to 13 bit (8,192 ppr)
- Industry standard absolute, incremental, analogue and linear output formats
- Accuracy to ±0.3°
- Simple integration

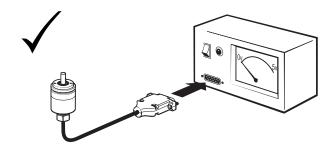
Storage and handling



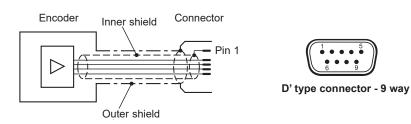
IMPORTANT: Power to RE22 encoders must be supplied from a DC SELV supply complying with the essential requirements of EN (IEC) 60950 or similar specification.

The RE22 series encoders have been designed to the relevant EMC standards, but must be correctly integrated to achieve EMC compliance. In particular, attention to shielding arrangements is critical.





Connections



	RE2		RE2		RE2	2DC	RE2	22IC	RE2		RE	22V
Pin nr.	Function	Wire colour	Function	Wire colour	Function	Wire colour	Function	Wire colour	Function	Wire colour	Function	Wire colour
1	Shie	eld - see conn	ection diagram	Shield	see connecti	on diagram	Shield - se	e connection of	liagram	Shield - see co	nnection diag	ram
2	V _A	Green	V _{A+}	Green	MA+	White	Z	White	Clock	White	NC	-
3	V _B	Brown	V _{B+}	Brown	MA-	Brown	В	Green	Clock-	Brown	V _{out}	Green
4	NC	-	NC	-	NC	-	А	Grey	NC	-	NC	-
5	V _{dd}	Red	V _{dd}	Red	V _{dd}	Red						
6	NC	-	V _{A-}	Yellow	SLO+	Green	Z–	Brown	Data	Green	NC	-
7	NC	-	V _{B-}	White	SLO-	Yellow	B-	Yellow	Data-	Yellow	NC	-
8	NC	-	NC	-	NC	-	A-	Pink	NC	-	NC	-
9	GND	Blue	GND	Blue	GND	Blue	GND	Blue	GND	Blue	GND	Blue

Operating and electrical specifications

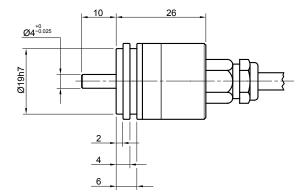
EMC compliance	EN 61326	
Cable	Outside diameter 5 mm , >R40 static bend radius	
Connector options	'D' type connector - 9 way Flying lead	
Mass	Encoder unit 1 m cable (no connector) IP53 axial cable 68 g, side cable 60 g.	
Environmental sealing	IP53 EN 60529:1992	

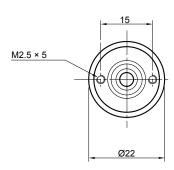


Installation drawingDimensions and tolerances in mm

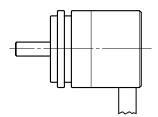
IP53

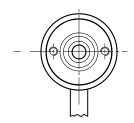
Axial cable exit





Radial cable exit





Special option 06 Flat, D-shaped shaft

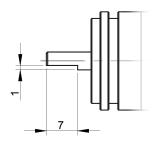


Table of expected bearing life ratings in hours

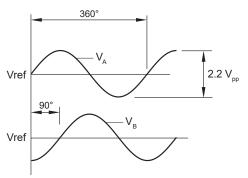
Speed (rpm)	Rad. load 5 N	Rad. load 10 N	Rad. load 15 N	Rad. load 20 N
500	205,401	98,455	54,569	33,333
1,000	102,700	49,227	27,285	16,667
2,000	51,350	24,613	13,642	8,333
5,000	20,540	9,845	5,457	3,333
10,000	10,270	4,923	2,728	1,667
15,000	6,847	3,282	1,819	1,111
30,000	5,135	2,461	1,364	833

Maximum recommended shaft loads: radial 20N, axial 10N

RE22AC – Analogue sinusoidal outputs 2 channels V_{A} V_{B} sinusoids (90° phase shifted, single ended)

Power supply	$V_{dd} = 5 V \pm 5 \%$
Power consumption	30 mA
Outputs	Single ended
	Signal amplitude $2.2 \pm 0.2 \text{ V}_{pp}$ Signal offset (Vref) $2.5 \text{ V} \pm 1 \text{ \%}$
Internal serial impedance	10 Ω
Maximum speed	30,000 rpm
Maximum cable length	3 m
Operating temperature	–40 °C to +120 °C

Timing diagram

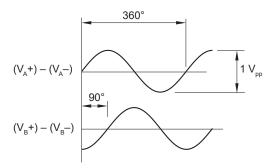


 $V_{\scriptscriptstyle A}$ leads $V_{\scriptscriptstyle B}$ by 90° for clockwise rotation of magnetic actuator.

RE22BC – Analogue complementary sinusoidal outputs 2 channels V_A and V_B differential sinusoids in quadrature (90° phase shifted)

Power supply	$V_{dd} = 5 V \pm 5 \%$
Power consumption	30 mA
Outputs	Differential
	Signal amplitude $0.5 \pm 0.1 \text{ V}_{pp}$ Signal offset (Vref) $0 \pm 5 \text{ mV}$
Internal serial impedance	10 Ω
Maximum speed	30,000 rpm
Maximum cable length	20 m
Operating temperature	–40 °C to +120 °C

Timing diagram



 $\rm V_{A}$ leads $\rm V_{B}$ by 90° for clockwise rotation of magnetic actuator.



RE22DC - Absolute natural binary BiSS C interface

Output code	Natural binary
Power supply	$V_{dd} = 5 V \pm 5 \%$
Current consumption	Max. 50 mA
Clock input	MA (RS422)
Data output	SLO (RS422)
Accuracy	Typ. ±0.5°
Hysteresis	0.18°
Resolution	320, 400, 500, 512, 800, 1,000, 1,024, 1,600, 2,000, 2,048, 4,096, 8,192 positions per revolution
Revolution counter	12 bit (4096 revolutions)
Maximum speed	30,000 rpm
Operating temperature	–40 °C to +120 °C
Max MA frequency	8 MHz

Timing diagram - BiSS C



Data	Length	Description
P11 – P0	0 or 12 bit	Revolution counter value when enabled (see Part numbering/ resolution)*
S12 – S0	7 to 13 bit	Position inside the revolution (length depends on the resolution)
E1 – E0	2 bit	Error data
CRC5 – CRC0	5 to 6 bit	Cyclic redundancy check data; polynomial 0x43; inverted bit output

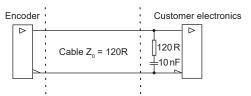
Error	E0	E1
No error	1	1
Amplitude error	0	1
Too high velocity	1	0
Undervoltage; Configuration; System error	0	0

^{*} The revolution counter counts the number of mechanical revolutions of the shaft or magnet of the encoder. Counting is possible only when the encoder is powered. When the encoder is powered off, the revolution counter is reset to 0.

For more information on BiSS C protocol please visit www.biss-interface.com.

Recommended signal termination

For data output lines only

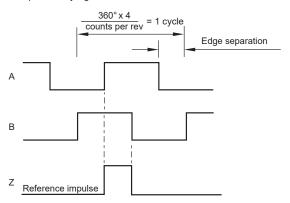


RE22D01_10

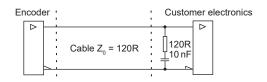
RE22IC – Incremental outputs Square wave differential line driver to RS422

Power supply	$V_{dd} = 5 V \pm 5 \%$
Power consumption	Max. 35 mA
Output signals	A, B, Z, A-, B-, Z- (RS422)
Accuracy	Typ. ±0.5°
Hysteresis	0.18°
Resolution	80 to 2,048 pulses per revolution (320, 400, 500, 512, 800, 1,000, 1,024, 1,600, 2,000, 2,048, 4,096, 8,192 counts per revolution)
Maximum speed	30,000 rpm
Maximum cable length	50 m
Operating temperature	−40 °C to +120 °C

Timing diagramComplementary signals not shown



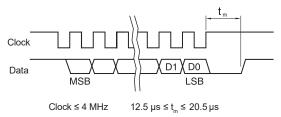
Recommended signal termination



RE22SC – Absolute binary synchro-serial interface (SSI) Serial encoded absolute position measurement

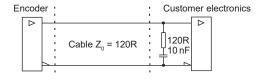
Output code	Natural binary
Power supply	V _{dd} = 5 V ±5 %
Power consumption	Max. 35 mA
Data output	Serial data (RS422)
Data input	Clock (RS422)
Accuracy	Typ. ±0.5°
Hysteresis	0.18°
Resolution	320, 400, 500, 512, 800, 1,000, 1,024, 1,600, 2,000, 2,048, 4,096, 8,192 positions per revolution
Maximum speed	30,000 rpm
Maximum cable length	100 m (at 1 MHz)
Operating temperature	-40 °C to +120 °C

Timing diagram



Recommended signal termination

For data output lines only





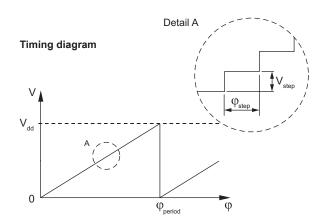
RE22Vx – Linear voltage output

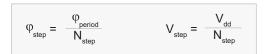
$V_{dd} = 5 V \pm 5 \%$
Typ. 26 mA
0 V to V _{dd}
Max. 10 mA
1 %
30,000 rpm
20 m
-40 °C to +120 °C

φ _{period}	N _{period}	N _{step}	ϕ_{step}
360°	1	1,024	0.35°
180°	2	1,024	0.18°
90°	4	1,024	0.09°
45°	8	512	0.09°

Output type and electrical variant

φ _{period} Rotation	360°	180°	90°	45°
Clockwise	VA	VB	VC	VD
Counterclockwise	VE	VF	VG	VH





 $\begin{array}{ll} \phi_{\text{period}} &=& \text{Angle covered in one period (one sawtooth)} \\ V_{\text{period}} &=& \text{Output voltage range for one period} \\ \phi_{\text{step}} &=& \text{Step angle (angular movement needed to register} \end{array}$ a change in the position)

V_{step} = Output voltage range for one step
N_{period} = Number of periods in one revolution
N_{step} = Number of steps in one period

RE22D01 10

Part numbering



Encoder part number eg RE22SC0409B10A3A00

RE22 SC 04 09B 10 A 3 A 00 Output type Special requirements AC - Analogue sinusoidal 2 V_{pp} BC - Analogue complementary sinusoidal 00 - None 06 - With flat, D-shaped shaft DC - Absolute natural binary BiSS C, RS422 0M - Cable length in meters IC - Incremental, RS422 SC - Absolute binary synchro-serial (SSI), RS422 Vx - Linear voltage: **Environment and material** A - IP53, aluminium body (standard) Linear voltage output 0 - 5 V, supply 5 V DC 180° 90° 45° Body style and cable exit CW VΒ VC ۷D 2 - Cylindrical body, radial cable exit 3 - Cylindrical body, axial cable exit VF VΗ CCW VΕ VG Connector option A - 'D' type connector - 9 way F - Flying lead (no connector) Shaft size **04** - 4 mm Resolution -For output types AC and BC: Cable length 01S - One sine/cosine wave per revolution 10 - 1.0 meter (10 meters if **0M** is chosen) For output type Vx: 10B - 1,024 positions per revolution

For output types **DC** with enabled 12 bit revolution counter:

Decimal

D80 - 800

1D0 - 1000

1D6 - 1600

D32 - 320

D40 - 400

D50 - 500

Decimal			Binary		
M32 - 320	M80 - 800	2M0 - 2000	09M - 512	12M - 4096	
M40 - 400	1M0 - 1000		10M - 1024	13M - 8192	
M50 - 500	1M6 - 1600		11M - 2048		

For output types DC, IC and SC (counts or positions per revolution):

2D0 - 2000

Binary

12B - 4096

13B - 8192

09B - 512

10B - 1024

11B - 2048

NOTE: Not all combinations are valid.

Series	Output type	Shaft size	Resolution	Cable length	Connector option	Body style and cable exit	Environment	Special requirements
	AC	04	01S	10	A/F	2/3	A	00 / 06 / 0M
	ВС							
RE22	DC		09B / D50 / D40 / D32 / 10B / 1D0 / D80 / 11B / 2D0 / 1D6 /12B / 13B 09M / M50 / M40 / M32 / 10M / 1M0 / M80 / 11M / 2M0 / 1M6 /12M / 13M					
	IC		09B / D50 / D40 / D32 / 10B / 1D0 / D80 / 11B / 2D0 / 1D6 /12B / 13B					
	SC							
	Vx		10B					



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Document issues

Issue	Date	Page	Corrections made	
1	13. 1. 2011	-	New document	
2	9. 7. 2015	2	Storage and handling info added; connections diagram and table added	
	3 4-6 6		Installation drawing tolerances updated, flat D-shaped shaft drawing added	
			Temperature range amended	
			Parallel output removed	
		7	Parallel output removed, resolution options updated and special option 06 added	
3	18. 5. 2018	5	Resolutions amended	
4	4. 7. 2018	General	Resolutions amended	
5	28. 2. 2019	3	IP64/68 radial cable exit drawing removed	
6	2. 10. 2019	1	Speed changed	
7	2. 2. 2022	General	DC output added	
8	19. 5. 2022	2	DC output wire color amended, cable data amended	
		General	IP64/IP68 deleted	
9	19. 1. 2023	4	BC output temperature amended, revolution counter added	
10	12. 9. 2023	5	DC output temperature amended	

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