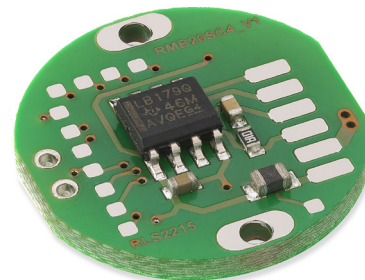
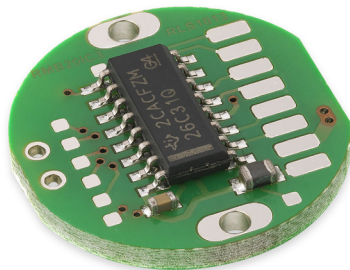


RMB20 encoder module with AM4096



The RMB20 encoder module provides the functionality of the RM22 encoder in a compact component format for simple customer integration. With a PCB diameter of only 20 mm, the module fits into miniature designs.

The encoder module consists of a magnetic actuator and a separate sensor board. Custom encoder chip that is mounted on a sensor board reads and processes the rotation of magnetic actuator and gives the required output format. Output signals are provided in industry standard absolute, incremental, analogue, commutation and linear formats.

The RMB20 can be designed into equipment used in a wide range of applications including marine, medical, print, converting, industrial automation, motor control and instrumentation.

Product range

RMB20AC/BC

Analogue sinusoidal outputs with a single sine/cosine period per revolution.

RMB20IC

Incremental with 8 to 1024 pulses per revolution (32 to 4096 counts per revolution with x4 evaluation).

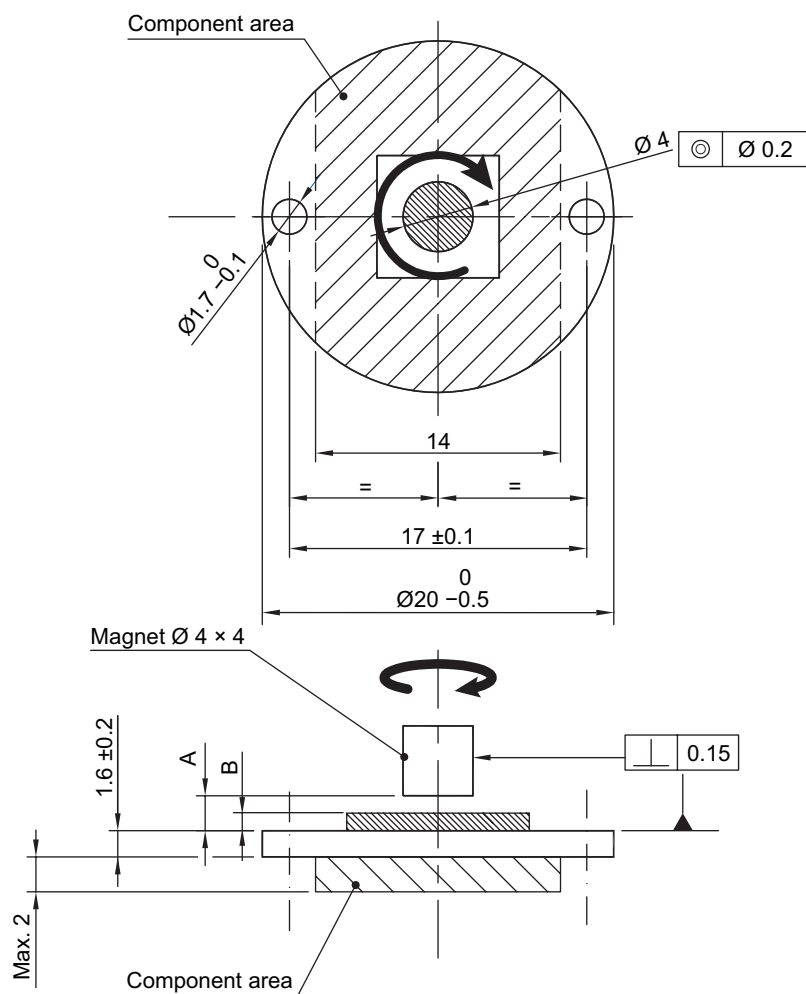
RMB20SC

Synchro serial interface (SSI) with 32 to 4096 positions per revolution.

The encoder module includes zeroing pads for setting the encoder zero position. The new zero position can be set by shorting the two zeroing pads.

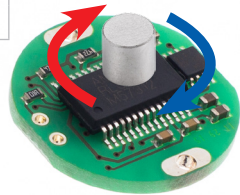
- Price performance solution
- 20 mm diameter circular module
- 5 V power supply
- High speed operation to 60,000 rpm
- Absolute - up to 12 bit resolution
- Industry standard absolute and incremental output formats
- Accuracy to $\pm 0.5^\circ$

Installation drawing



Module	A PCB surface to magnet distance [mm]	B Chip height [mm]
RMB20AC	2.30 ± 0.5	Max. 1
RMB20BC		
RMB20IC	2.8 ± 0.5	Max. 2
RMB20SC		

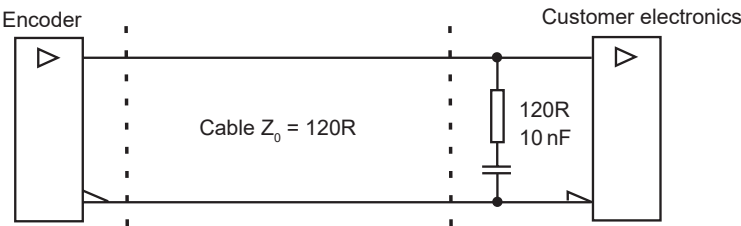
NOTE: For the accuracy specified, the central line of the magnet needs to be square to the chip within 2° and aligned within the center of the board ±0.1 mm (mid point between the two mounting holes).



Clockwise (CW) rotation of magnet

Recommended signal termination

For data output lines only



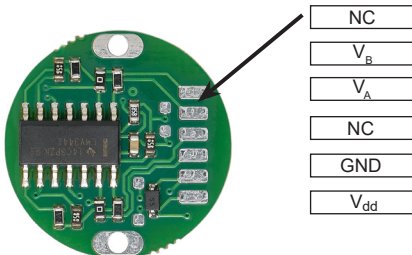
RMB20AC – Analogue sinusoidal outputs

2 channels V_A and V_B sinusoids (90° phase shifted, single ended)

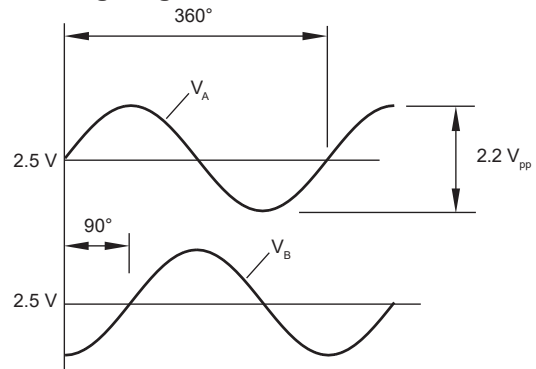
Power supply	$V_{dd} = 5\text{ V} \pm 5\%$
Current consumption	30 mA
Outputs	Single ended
Signal amplitude	$2.2 \pm 0.2\text{ V}_{pp}$
Signal offset (Vref)	$2.5\text{ V} \pm 1\%$
Internal serial impedance	$10\ \Omega$
Maximum speed	60,000 rpm
Temperature Operating and storage	$-40\text{ }^\circ\text{C}$ to $+125\text{ }^\circ\text{C}$

Connections

RMB20AC



Timing diagram



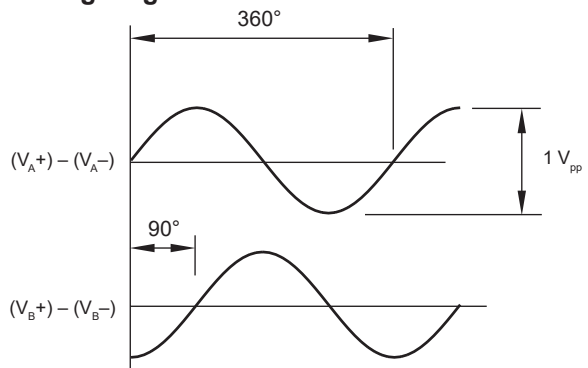
V_A leads V_B for clockwise rotation of magnet

RMB20BC – Analogue complementary sinusoidal outputs

2 channels V_A and V_B differential sinusoids

Power supply	$V_{dd} = 5\text{ V} \pm 5\%$
Current consumption	30 mA
Outputs	Differential
Signal amplitude	$0.5 \pm 0.1\text{ V}_{pp}$
Signal offset (Vref)	$0 \pm 5\text{ mV}$
Internal serial impedance	$10\ \Omega$
Maximum speed	60,000 rpm
Temperature Operating and storage	$-40\text{ }^\circ\text{C}$ to $+125\text{ }^\circ\text{C}$

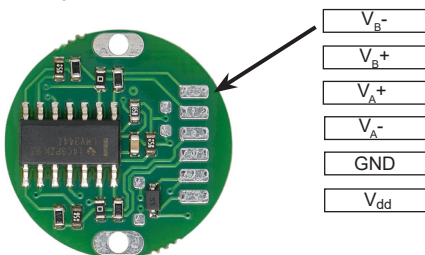
Timing diagram



V_A leads V_B for clockwise rotation of magnet

Connections

RMB20BC



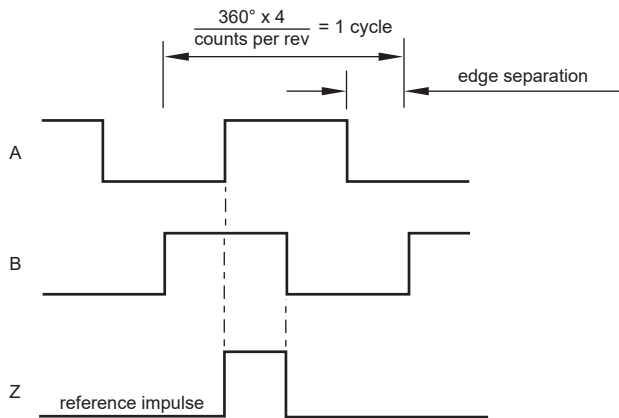
RMB20IC – Incremental output

Square wave differential line driver to RS422

Power supply	$V_{dd} = 5\text{ V} \pm 5\%$
Current consumption	35 mA
Output signals	A, B, Z, A–, B–, Z– (RS422)
Resolutions	32, 64, 128, 256, 512, 1,024, 2,048, 4,096 cpr
Maximum speed	60.000 for resolutions up to 1,024 cpr 30.000 for 2,048 and 4,096 cpr
Accuracy	$\pm 0.5^\circ$
Hysteresis	0.18°
Temperature	-40°C to $+125^\circ\text{C}$
Operating and storage	

Timing diagram

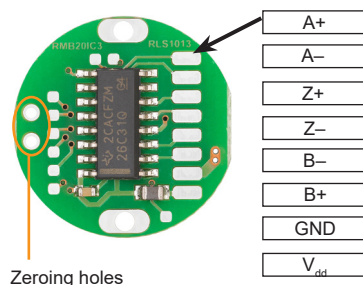
Complementary signals not shown



B leads A for clockwise rotation of magnet.

Connections

RMB20IC

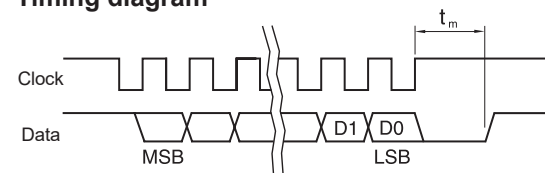


RMB20SC – Absolute binary synchro-serial interface (SSI)

Serial encoded absolute position measurement

Output code	Natural binary
Power supply	$V_{dd} = 5\text{ V} \pm 5\%$
Current consumption	35 mA
Resolutions	512, 1,024, 2,048, 4,096 positions per revolution
Repeatability	$\leq 0.07^\circ$
Data output	Serial data (RS422)
Data input	Clock (RS422)
Temperature	-40°C to $+125^\circ\text{C}$
Operating and storage	

Timing diagram

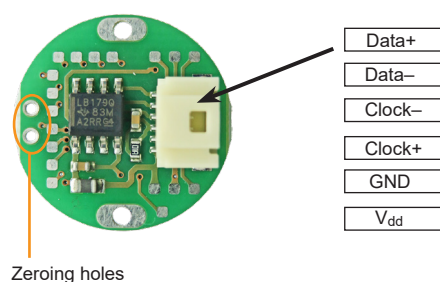
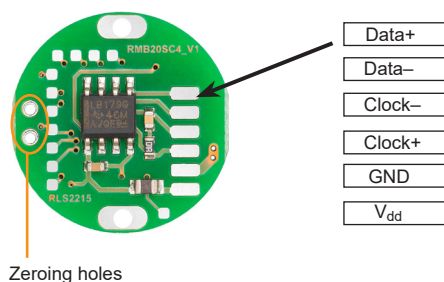


Clock $\leq 4\text{ MHz}$ $12.5\text{ }\mu\text{s} \leq t_m \leq 20.5\text{ }\mu\text{s}$

Position increases for clockwise rotation of magnet.

Connections

RMB20SC



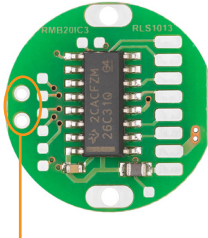
Connector type: Molex 501568-0607
Mating connector: Molex 501330-0600
Crimp terminal: 501334-0000

Zero position setting procedure

Encoder zero position can be easily set by shortening the zeroing pads on the board. After locking the motor at the mechanical zero position short together the two zeroing pads.

The output angle position data can be zeroed at any angle with resolution of 0.0879°.

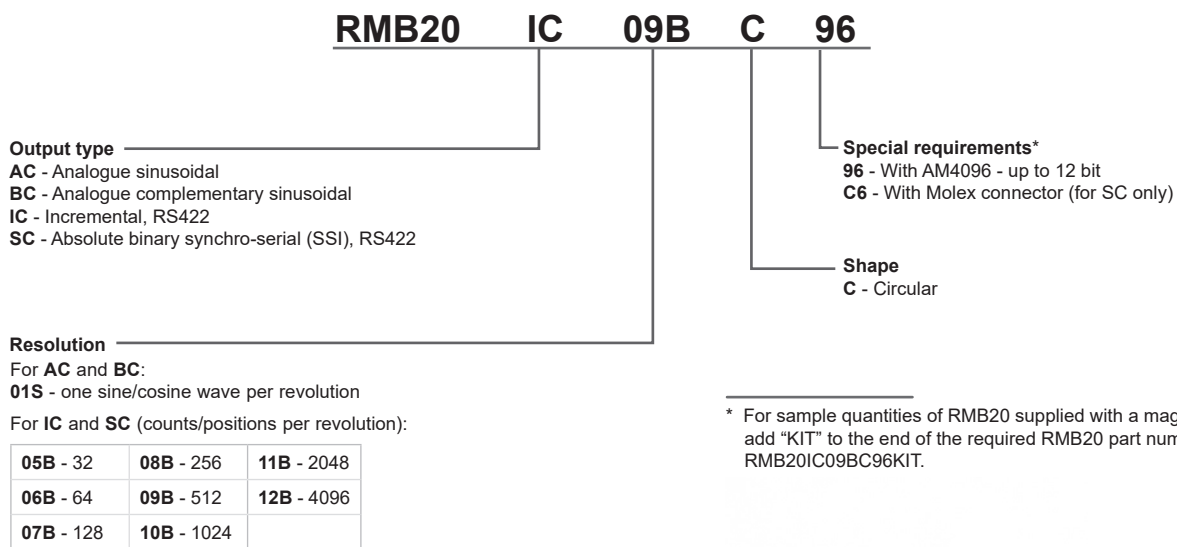
RMB20 zeroing example



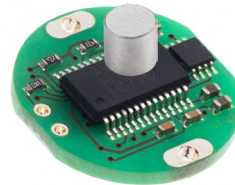
zeroing holes

The zeroing holes can be shorted to set the zero position of the encoder.

Part numbering

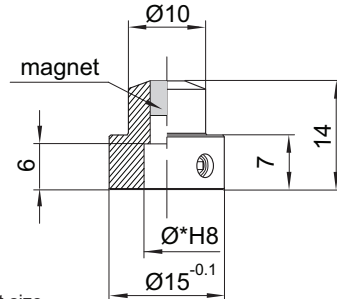


* For sample quantities of RMB20 supplied with a magnet please add "KIT" to the end of the required RMB20 part number, eg. RMB20IC09BC96KIT.



Magnetic actuator and magnet ordering information

Actuator for integration onto shaft



Shaft = Ø*h7

Fixing: Grub screw provided

* Hole diameter for nominal shaft size.
See table on the right for more
information on available shaft sizes.

Part numbers:

For resolutions up to 9 bit absolute (512 cpr incremental)

RMA04A2A00 – Ø4 mm shaft	RMA10A2A00 – Ø10 mm shaft
RMA05A2A00 – Ø5 mm shaft	RMA19A2A00 – Ø3/16" shaft
RMA06A2A00 – Ø6 mm shaft	RMA25A2A00 – Ø1/4" shaft
RMA08A2A00 – Ø8 mm shaft	RMA37A2A00 – Ø3/8" shaft

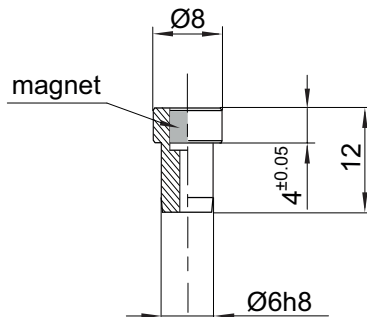
For resolutions from 10 bit absolute (800 cpr incremental) and above

RMA04A3A00 – Ø4 mm shaft	RMA10A3A00 – Ø10 mm shaft
RMA05A3A00 – Ø5 mm shaft	RMA19A3A00 – Ø3/16" shaft
RMA06A3A00 – Ø6 mm shaft	RMA25A3A00 – Ø1/4" shaft
RMA08A3A00 – Ø8 mm shaft	RMA37A3A00 – Ø3/8" shaft

Actuator for integration into shaft



with N-pole
marker



Hole = Ø6G7

Fixing: Glue (recommended – LOCTITE 648 or 2701)

Part numbers:

For resolutions up to 9 bit absolute (512 cpr incremental)

RMH06A2A00

For resolutions from 10 bit absolute (800 cpr incremental) and above

RMH06A3A00

With N-pole marker scribed to a ±5° accuracy:

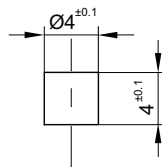
For resolutions up to 9 bit absolute (512 cpr incremental)

RMH06A2A02

For resolutions from 10 bit absolute (800 cpr incremental) and above

RMH06A3A02

Magnet for direct recessing in non-ferrous shafts



Fixing: Glue (recommended – LOCTITE 648 or 2701)

Part numbers:

For resolutions up to 9 bit absolute (512 cpr incremental)

RMM44A2A00 (individually packed) – for sample quantities only
RMM44A2C00 (packed in tubes)

For resolutions from 10 bit absolute (800 cpr incremental) and above

RMM44A3A00 (individually packed) – for sample quantities only
RMM44A3C00 (packed in tubes)

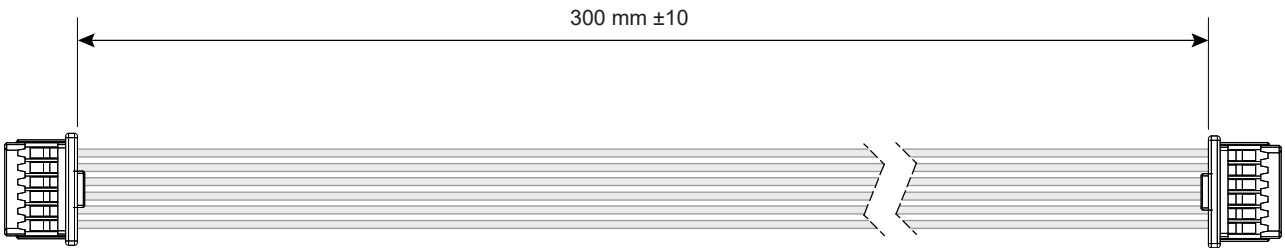
Accessories part numbering

Cable assembly with dual ended connectors

Cable specifications for connection of Molex 501330-0600

Part numbers	ACC028 (cable length: 30 cm)
Number of wires	6
Wire size	28 AWG
Wire insulation diameter	0.6 mm
Wire type	UL 1571
Connector	Molex 501330-0600
Crimp terminal	501334-0000
Mating connector type	Molex 501568-0607

Dimensions



→ MOLEX 501330-0600



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Document issues

Issue	Date	Page	Amendments done
1	29. 4. 2016	-	New document
2	14. 7. 2016	3	Zeroing pads added
3	2. 6. 2017	1	RoHS logo added
		4	Zeroing procedure added
4	26. 3. 2019	3	Molex connector for RMB20SC added
5	30. 8. 2019	2	Dimensions drawing amended
		6	Cable accessories amended
6	27. 9. 2021	2	Dimensions drawing amended
		3	Temperature SC amended
7	6. 12. 2021	1, 2, 3, 5	AC / BC output added
8	10. 3. 2022	3	AB / BC output amended

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