

# **RE22 rotary magnetic shaft encoder**



The RE22 is a compact, high-speed rotary magnetic encoder designed for use in harsh environments. The traditional design allows for easy integration to existing machines.

A magnet is mounted to the shaft within the encoder body. Rotation of this magnet is sensed by a custom encoder chip within the body, and processed to give the required output format.

The encoder chip processes the signals received to provide resolutions of up to 13 bit (8,192 positions per revolution) with high operational speeds. Output signals are provided in industry standard absolute, incremental, analogue or linear formats.

The compact encoder body is just 22 mm in diameter and provides dirt immunity up to IP53.

The RE22 can be used in a wide range of applications including marine, medical, print, converting, industrial automation, metal working and instrumentation.

### Product range RE22AC

Analogue with a single sin e/cosine cycle per revolution

### RE22BC

Complementary analogue outputs with a single sine/cosine cycle per revolution

### RE22DC

BiSS C interface with up to 8,192 positions per revolution and optional revolution counter

### RE22IC

Incremental with 80 to 2,048 pulses per revolution (320 to 8,192 counts per revolution with x 4 evaluation)

### RE22SC

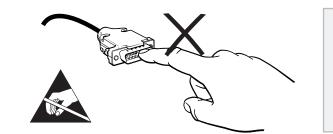
Synchro serial interface (SSI) with 320 to 8,192 positions per revolution

#### RE22Vx

Linear voltage output in a range of variants

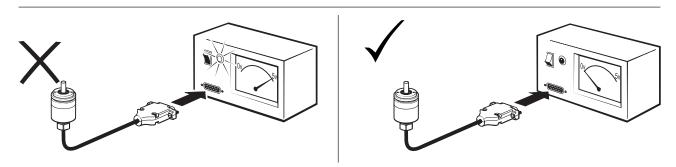
- High speed operation to 30,000 rpm
- Compact 22 mm diameter body
- Absolute to 13 bit (8,192 ppr)
- Industry standard absolute, incremental, analogue and linear output formats
- Accuracy to ±0.3°
- Simple integration

## Storage and handling

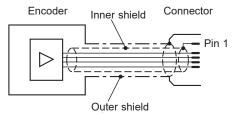


**IMPORTANT:** Power to RE22 encoders must be supplied from a DC SELV supply complying with the essential requirements of EN (IEC) 60950 or similar specification.

The RE22 series encoders have been designed to the relevant EMC standards, but must be correctly integrated to achieve EMC compliance. In particular, attention to shielding arrangements is critical.



### Connections





D' type connector - 9 way

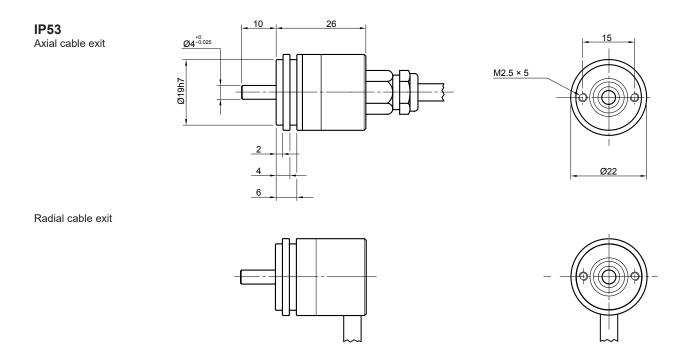
	RE2	2AC	RE2	2BC	RE2	2DC	RE2	22IC	RE2	2SC	RE	22V
Pin nr.	Function	Wire colour	Function	Wire colour	Function	Wire colour	Function	Wire colour	Function	Wire colour	Function	Wire colour
1	Shi	eld - see conn	ection diagram	n Shield -	- see connecti	on diagram	Shield - se	e connection of	liagram	Shield - see co	onnection diag	ram
2	V <sub>A</sub>	Green	V <sub>A+</sub>	Green	MA+	White	Z	White	Clock	White	NC	-
3	V <sub>B</sub>	Brown	V <sub>B+</sub>	Brown	MA-	Brown	В	Green	Clock-	Brown	V <sub>out</sub>	Green
4	NC	-	NC	-	NC	-	A	Grey	NC	-	NC	-
5	V <sub>dd</sub>	Red	V <sub>dd</sub>	Red	V <sub>dd</sub>	Red						
6	NC	-	V <sub>A-</sub>	Yellow	SLO+	Green	Z–	Brown	Data	Green	NC	-
7	NC	-	V <sub>B-</sub>	White	SLO-	Yellow	В-	Yellow	Data-	Yellow	NC	-
8	NC	-	NC	-	NC	-	A-	Pink	NC	-	NC	-
9	GND	Blue	GND	Blue	GND	Blue	GND	Blue	GND	Blue	GND	Blue

### **Operating and electrical specifications**

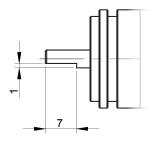
EMC compliance	EN 61326
Cable	Outside diameter 5 mm , >R40 static bend radius
Connector options	ʻD' type connector - 9 way Flying lead
Mass	Encoder unit 1 m cable (no connector) IP53 axial cable 68 g, side cable 60 g.
Environmental sealing	IP53 EN 60529:1992



# Installation drawing Dimensions and tolerances in mm



# **Special option 06** Flat, D-shaped shaft



### Table of expected bearing life ratings in hours

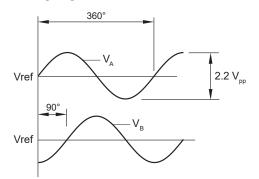
Speed (rpm)	Rad. load 5 N	Rad. load 10 N	Rad. load 15 N	Rad. load 20 N
500	205,401	98,455	54,569	33,333
1,000	102,700	49,227	27,285	16,667
2,000	51,350	24,613	13,642	8,333
5,000	20,540	9,845	5,457	3,333
10,000	10,270	4,923	2,728	1,667
15,000	6,847	3,282	1,819	1,111
30,000	5,135	2,461	1,364	833

Maximum recommended shaft loads: radial 20N, axial 10N

## $\begin{array}{l} \textbf{RE22AC-Analogue sinusoidal outputs} \\ \textbf{2 channels } V_{A} \, V_{B} \, \text{sinusoids (90° phase shifted, single ended)} \end{array}$

Power supply	$V_{dd} = 5 V \pm 5 \%$
Power consumption	30 mA
Outputs	Single ended
	Signal amplitude 2.2 $\pm$ 0.2 V <sub>pp</sub> Signal offset (Vref) 2.5 V $\pm$ 1 %
Internal serial impedance	10 Ω
Maximum speed	30,000 rpm
Maximum cable length	3 m
Operating temperature	–40 °C to +120 °C

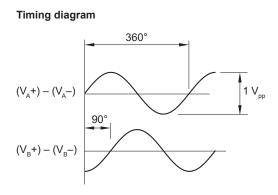
Timing diagram



 $V_{\scriptscriptstyle A}$  leads  $V_{\scriptscriptstyle B}$  by 90° for clockwise rotation of magnetic actuator.

# $\begin{array}{l} \textbf{RE22BC-Analogue complementary sinusoidal outputs} \\ \textbf{2 channels } V_{A} \text{ and } V_{B} \text{ differential sinusoids in quadrature (90° phase shifted)} \end{array}$

Power supply	$V_{dd} = 5 V \pm 5 \%$
Power consumption	30 mA
Outputs	Differential
	Signal amplitude  0.5 ±0.1 V <sub>pp</sub> Signal offset (Vref) 0 ±5 mV
Internal serial impedance	10 Ω
Maximum speed	30,000 rpm
Maximum cable length	20 m
Operating temperature	–40 °C to +120 °C



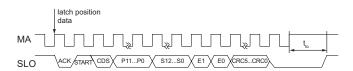
 $V_{\scriptscriptstyle A}$  leads  $V_{\scriptscriptstyle B}$  by 90° for clockwise rotation of magnetic actuator.



### RE22DC – Absolute natural binary BiSS C interface

Output code	Natural binary
Power supply	$V_{dd} = 5 V \pm 5 \%$
Current consumption	Max. 50 mA
Clock input	MA (RS422)
Data output	SLO (RS422)
Accuracy	Typ. ±0.5°
Hysteresis	0.18°
Resolution	320, 400, 500, 512, 800, 1,000, 1,024, 1,600, 2,000, 2,048, 4,096, 8,192 positions per revolution
Develotion constant	
Revolution counter	12 bit (4096 revolutions)
Maximum speed	12 bit (4096 revolutions) 30,000 rpm
	, , ,
Maximum speed	30,000 rpm

### Timing diagram – BiSS C



Data	Length	Description
P11 – P0	0 or 12 bit	Revolution counter value when enabled (see Part numbering/ resolution)*
S12 – S0	7 to 13 bit	Position inside the revolution (length depends on the resolution)
E1 – E0	2 bit	Error data
CRC5 – CRC0	5 to 6 bit	Cyclic redundancy check data; polynomial 0x43; inverted bit output

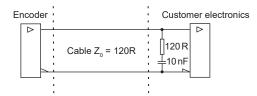
Error	E0	E1
No error	1	1
Amplitude error	0	1
Too high velocity	1	0
Undervoltage; Configuration; System error	0	0

\* The revolution counter counts the number of mechanical revolutions of the shaft or magnet of the encoder. Counting is possible only when the encoder is powered. When the encoder is powered off, the revolution counter is reset to 0.

For more information on BiSS C protocol please visit <u>www.biss-interface.com</u>.

#### **Recommended signal termination**

For data output lines only

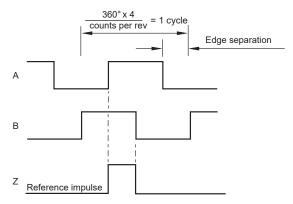


## **RE22IC – Incremental outputs** Square wave differential line driver to RS422

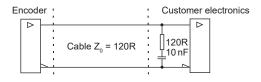
Power supply	$V_{dd} = 5 V \pm 5 \%$
Power consumption	Max. 35 mA
Output signals	A, B, Z, A–, B–, Z– (RS422)
Accuracy	Typ. ±0.5°
Hysteresis	0.18°
Resolution	80 to 2,048 pulses per revolution (320, 400, 500, 512, 800, 1,000, 1,024, 1,600, 2,000, 2,048, 4,096, 8,192 counts per revolution)
Maximum speed	30,000 rpm
Maximum cable length	50 m
Operating temperature	−40 °C to +120 °C







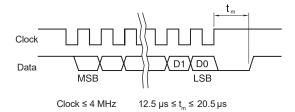
#### **Recommended signal termination**



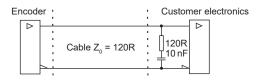
# RE22SC – Absolute binary synchro-serial interface (SSI) Serial encoded absolute position measurement

Output code	Natural binary		
Power supply	V <sub>dd</sub> = 5 V ±5 %		
Power consumption	Max. 35 mA		
Data output	Serial data (RS422)		
Data input	Clock (RS422)		
Accuracy	Typ. ±0.5°		
Hysteresis	0.18°		
Resolution	320, 400, 500, 512, 800, 1,000, 1,024, 1,600, 2,000, 2,048, 4,096, 8,192 positions per revolution		
Maximum speed	30,000 rpm		
Maximum cable length	100 m (at 1 MHz)		
Operating temperature	-40 °C to +120 °C		

Timing diagram



#### **Recommended signal termination** For data output lines only





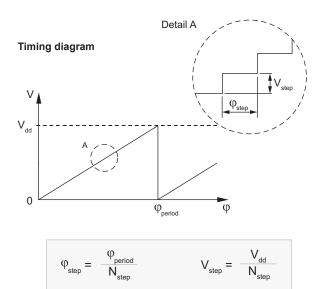
### RE22Vx – Linear voltage output

Power supply	$V_{dd} = 5 V \pm 5 \%$
Power consumption	Typ. 26 mA
Output voltage	0 V to V <sub>dd</sub>
Output loading	Max. 10 mA
Nonlinearity	1 %
Maximum speed	30,000 rpm
Maximum cable length	20 m
Operating temperature	-40 °C to +120 °C
<b>~</b>	

N<sub>period</sub> N<sub>step</sub>  $\boldsymbol{\phi}_{\mathsf{period}}$  $\boldsymbol{\phi}_{\mathsf{step}}$ 0.35° 360° 1,024 1 180° 2 1,024 0.18° 90° 4 1,024 0.09° 45° 8 512 0.09°

### Output type and electrical variant

φ <sub>period</sub> Rotation	360°	180°	90°	45°
Clockwise	VA	VB	VC	VD
Counterclockwise	VE	VF	VG	VH

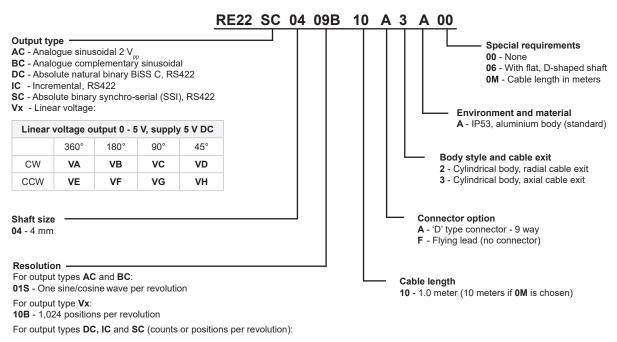


- = Angle covered in one period (one sawtooth)
- $\begin{array}{c} \phi_{\text{period}} \\ V_{\text{period}} \\ \phi_{\text{step}} \end{array}$ Output voltage range for one periodStep angle (angular movement needed to register a change in the position)
  - = Output voltage range for one step
  - Number of periods in one revolution
    Number of steps in one period
- V<sub>step</sub> N<sub>period</sub> N<sub>step</sub>

### Part numbering



Encoder part number eg RE22SC0409B10A3A00



Decimal			Binary		
<b>D32</b> - 320	<b>D80</b> - 800	<b>2D0 -</b> 2000	<b>09B -</b> 512	<b>12B</b> - 4096	
<b>D40</b> - 400	<b>1D0</b> - 1000		<b>10B</b> - 1024	<b>13B</b> - 8192	
<b>D50</b> - 500	<b>1D6</b> - 1600		<b>11B</b> - 2048		

For output types **DC** with enabled 12 bit revolution counter:

Decimal			Binary		
<b>M32 -</b> 320	<b>M80 -</b> 800	<b>2M0 -</b> 2000	<b>09M -</b> 512	<b>12M</b> - 4096	
<b>M40 -</b> 400	<b>1M0</b> - 1000		<b>10M -</b> 1024	<b>13M</b> - 8192	
<b>M50</b> - 500	<b>1M6</b> - 1600		<b>11M</b> - 2048		

NOTE: Not all combinations are valid.

Series	Output type	Shaft size	Resolution	Cable length	Connector option	Body style and cable exit	Environment	Special requirements
	AC		040	10 /	A/F	2/3	A	00 / 06 / 0M
	BC		01S					
RE22	DC	04	09B / D50 / D40 / D32 / 10B / 1D0 / D80 / 11B / 2D0 / 1D6 /12B / 13B 09M / M50 / M40 / M32 / 10M / 1M0 / M80 / 11M / 2M0 / 1M6 /12M / 13M					
	IC		09B / D50 / D40 / D32 / 10B / 1D0 / D80 / 11B / 2D0 / 1D6 /12B / 13B					
	SC							
	Vx		10B					



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#### **Document issues**

Issue	Date	Page	Corrections made	
1	13. 1. 2011	-	New document	
2	9. 7. 2015	2	Storage and handling info added; connections diagram and table added	
		3	Installation drawing tolerances updated, flat D-shaped shaft drawing added	
		4-6	Temperature range amended	
		6	Parallel output removed	
		7	Parallel output removed, resolution options updated and special option 06 added	
3	18. 5. 2018	5	Resolutions amended	
4	4. 7. 2018	General	Resolutions amended	
5	28. 2. 2019	3	IP64/68 radial cable exit drawing removed	
6	2. 10. 2019	1	Speed changed	
7	2. 2. 2022	General	DC output added	
8	19. 5. 2022	2	DC output wire color amended, cable data amended	
		General	IP64/IP68 deleted	
9	19. 1. 2023	4	BC output temperature amended, revolution counter added	

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