

### **LM13**

# Incremental Magnetic Encoder

UNIQUE REFERENCE MARK

The LM13 is a high-speed, non-contact magnetic rotary encoder system designed for linear or rotary motion in harsh environments. If features a compact readhead and a self-adhesive magnetic scale or ring.

SMALL SIZE AND SIMPLE INTEGRATION

Simple to install, the LM13 features a set-up LED and large mounting tolerances. The encoder is available with digital or analogue output variants and offers a range of customer-selectable resolutions from 0.244  $\mu m$  to 250  $\mu m$  or from 25 dpi to 25,600 dpi for printing applications.

WEAR-FREE MEASURING PRINCIPLE



### **Features and benefits**

- Customer selectable resolutions
- ► High speed operation
- ► Excellent dirt immunity to IP68
- Linear or rotary position sensing
- Non-contact and wear-free measuring principle
- ▶ Unique bidirectional reference mark
- ► CE compliant, including RoHS
- Integral set-up LED











### **General information**

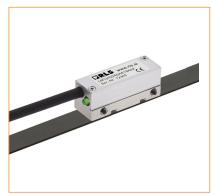
Engineered for extreme service, the solid-state LM13 linear encoders operate from –10 °C to +80 °C, have water-proof sealing to IP68 and are highly resistant to shock, vibration and pressure. The robust magnetic scale and ring are also resistant to various of chemicals commonly found in industry. The non-contact, frictionless design eliminates wear and reduces hysteresis.

### Choose your LM13 system

The robust LM13 readhead is compatible with the RLS MS10 incremental scale as well as the RLS axial and radial rings. You can select the length of the MS scale up to 150 m. There is also a wide range of axial and radial incremental rings available.

The LM13 readhead also comes in DPI version which is compatible with the MS12 incremental scale.

LM13 + magnetic scale



More about the MS magnetic scales can be found in the MSD01 at <u>RLS</u> <u>Media center.</u>

LM13 + radial ring



More about the radial rings can be found in the MR02D02 at **RLS Media center.** 

LM13 + axial ring



More about the axial rings can be found in the MR01D01 at **RLS Media center.** 



### Storage and handling

All data given below refer to the readhead only. Complete systems with magnetic scale or ring may have other limitations. For more information, see the MSD01, MR01D01 or MR02D02 data sheet at **RLS Media center.** 

#### Storage temperature



-40 °C to +85 °C

### **Operating temperature**



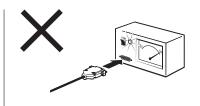
-10 °C to +80 °C

#### IP protection



IP68



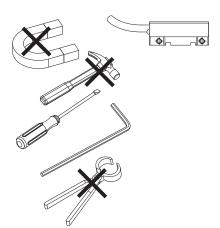






#### Readhead is ESD sensitive - handle with care.

Do not touch electronic circuit, wires or sensor area without proper ESD protection or outside of ESD controlled environment.



This encoder system is a high performance metrology product and must be handled carefully. The use of industrial tools during installation or exposure to strong magnets such as a magnetic base is not recommended as it carries the risk of damaging parts of the system which as a result might not perform in accordance with specifications.

### **Packaging**

Each readhead is packed individually in antistatic bag, according to ESD protection measures.

### Labeling

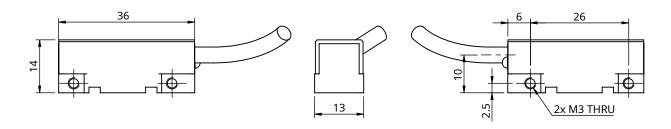


Label on the readhead contains: full PN, 6 digits long serial number and 2D code containing the serial number.

### **Dimensions**

Dimensions and tolerances are in mm. Dimensions without tolerance values are in accordance with ISO 2768-m.





3D model available for download at **RLS Media center.** 

### General tolerances for linear dimensions according to ISO 2768 m

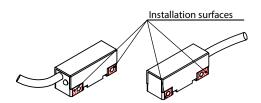
Tolerance class	up to 6	6-30	30-120
m (medium)	±0.1	±0.2	±0.3

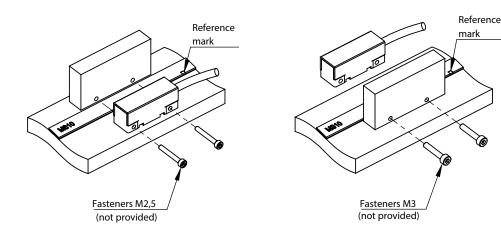


### **Installation instructions**

The readhead LED must be green at all measuring length positions. Otherwise, the installation is not performed correctly. The 0.1 mm to 1.0 mm thick plastic spacer (shim) can be used to facilitate installation. For optimal installation, the recommended thickness of the shim is 0.3 mm. After mounting the magnetic scale, place the plastic shim and the readhead on the magnetic scale. Make sure that the readhead, shim and magnetic scale are in full contact.

Improper mounting of the magnetic scale and readhead can impair the function of the magnetic encoder system and lead to total failure.





Images are for illustration purpose only. Valid for all versions.

#### Position of installation holes

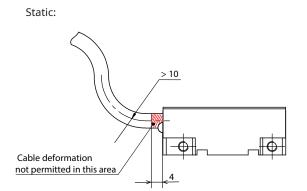
Recommended use of M3 fasteners with washers. For more information, see <u>Table of recommended fastener tightening</u> <u>torques</u> at <u>RLS Media center.</u>

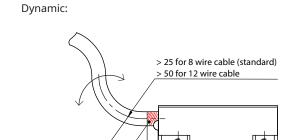
- All permissible distance and angle tolerances must be strictly complied according to the mounting instructions found at MSD01, MR01D01 or MR02D02 data sheet at <u>RLS Media center</u>.
- It is important that the space between the readhead and the magnetic scale is maintained over the entire measuring range.
- The magnetic encoder system must be used in accordance with the specified degree of protection. The following factors must be taken into account: IP protection class, operating temperature, external magnetic field, humidity level, mechanical load and EMC compatibility.
- The magnetic encoder system is sensitive to the external magnetic fields. The magnitude of the influence on the magnetic encoder system depends on the magnitude and direction of the external magnetic field. In particular, the rapidly changing stray magnetic fields affect the system and can alter its function. Magnetic field strength within 1 mT reduces the accuracy of the system. Field strengths greater than 1 mT will cause the system to malfunction and as a result the readhead will report an incorrect position with the red color LED. Magnetic field strengths greater than 25 mT will cause irreversible damage to the magnetic scale or ring and will have to be replaced.

### Cable installation

Dimensions and tolerances are in mm. Dimensions without tolerance values are in accordance with ISO 2768-m.







## **Technical specifications**

Dimensions and tolerances are in mm. Dimensions without tolerance values are in accordance with ISO 2768-m.

Cable deformation

not permitted in this area



### System data

Pole length		2 mm
Maximum measur	ing length	50 m (up to 150 m per request)
System accuracy	Linear application	±10 μm/m / ±20 μm/m / ±40 μm/m
	MS magnetic scale	Different accuracy grades of MS magnetic scale are available. Refer to
		MSD01 available at <b>RLS Media center.</b>
	Rotary application	Axial: Refer to MR01D01 available at RLS Media center.
		Radial: Refer to MR02D02 available at RLS Media center.
Hysteresis		< 4 µm up to 0.5 mm ride height
Repeatability		< 1 µm at 25°C
Reference mark		Unique / Periodic / DCRM (information about distance coded ref. mark can
		be found in the MSD01 at <b>RLS Media center</b> ).
Resolution		Max. 13 bit (~0.244 μm) For details refer to the <b>Table of available</b>
		<u>resolutions</u> .
Maximum speed	Linear application	Refer to MSD01 available at RLS Media center.
	Rotary application	Axial: Refer to MR01D04 available at RLS Media center.
		Radial: Refer to speed calculator available at RLS website.

### Electrical data

For electrical data see specific output type on pages 11 to 12



### Mechanical data

Mass	Readhead	23 g
Material	Readhead	Aluminium (Eloxal - anodised)

### Environmental data

Temperature	Operating	–10 °C to +80 °C (–20 °C to +85 °C if cable under non-dynamic conditions)	
	Storage	-40 °C to +85 °C	
Environmental s	ealing	IP68 (according to IEC 60529)*	
<b>EMC Immunity</b>		IEC 61000-6-2	
EMC Emission		IEC 61000-6-4	
Vibrations (55 Hz	to 2000 Hz)	300 m/s <sup>2</sup> (IEC 60068-2-6)	
Shocks (6 ms)		300 m/s <sup>2</sup> (IEC 60068-2-27)	
External magnetic field during operation		1 mT	

<sup>\*</sup>Limited by the connector.

### Cable

Туре	PUR high flexible cable, drag-chain compatible, double-shielded		
Number of wires	8	12**	
Outer diameter	4.2 mm ±0.2 mm	4.5 mm ±0.2 mm	
Jacket material	Extruded polyurethane (PUR)		
White wire	$0.14~\text{mm}^2$ , $26~\text{AWG}$ , $0.13~\Omega/\text{m}$	- 0.00 - 3.00 NMC 0.00 07	
Other wires	$0.05~\text{mm}^2$ , $30~\text{AWG}$ , $0.35~\Omega/\text{m}$	— 0.08 mm², 28 AWG, 0.23 Ω/m	
Durability	20 million cycles at 25 mm bend radius	20 million cycles at 50 mm	
		bend radius	
Weight	34 g/m nominal	38 g/m nominal	
Bend radius (internal radius)	Dynamic: 25 mm, static: 10 mm	Dynamic: 50 mm, static: 10 mm	
Dynamic torsion	Not allowed*		

<sup>\*</sup> Cable is not torsion specified. A continues torsion of the cable in a dynamic application could result in malfunctioning of the encoder system.

### **Cable tolerances**

Cable length* [m]	Tolerance [mm]
≤ 5	+50/–20
> 5 ≤ 10	+70/–30
> 10 ≤ 30	+100/–40

<sup>\*</sup>Cable length without connector.

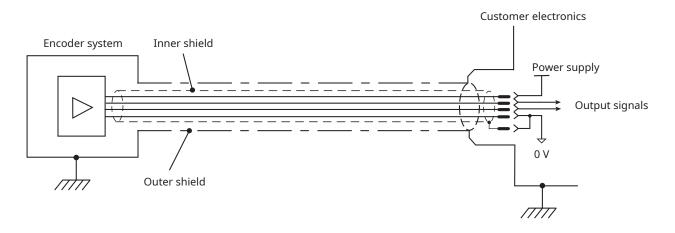
<sup>\*\*</sup> Applied only for option with additional alarm output (for IA, IC; not available for PRG option).

### **Electrical connections**

			9 pin D type plug ( <u>option A</u> )	15 pin D type plug ( <u>option D</u> )	9 pin CPC connector ( <u>option E</u> )	15 pin HD type plug ( <u>option H</u> )	15 pin D type plug ( <u>option L</u> )	9 pin D type plug ( <u>option P</u> )
Function	Signal	Colour ( <u>option F</u> )	(1	15.00 m m m m m m m m m m m m m m m m m m				(1
	5 V	Brown	5	7	8	7	4	5
Power	0 V	White	9	2	7	2	12	1
	A/V <sub>1</sub>	Green	4	14	1	14	9	2
Incremental	A- / V <sub>1</sub> -	Yellow	8	6	4	6	1	6
/ analogue signals	B/V <sub>2</sub>	Blue	3	13	2	13	10	4
	B- / V <sub>2</sub> -	Red	7	5	5	5	2	8
Reference	Z/V <sub>o</sub>	Pink	2	12	3	12	3	3
signals	Z- / V <sub>0</sub> -	Grey	6	4	6	4	11	7
Alarm	E	Violet	-	11	-	11	-	-
For 07 option only	E-	Black	-	3	-	3	-	-
	Inner	-	1	15	7	15	15	9
Shield	Outer	-	Case	Case	9	Case	Case	Case

### Shield connection

Figure below shows a recommended shield termination in order to ensure electromagnetic compatibility.



Housing of the encoder is galvanically connected with the housing of the connector via the cable outer shield. The encoder system must be correctly integrated to achieve EMC compliance. In particular, attention to shielding arrangements is essential.



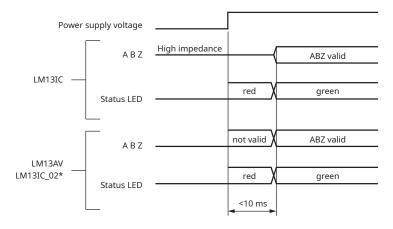
### **Response time**

	LM13AV	LM13IC_02	LM13IC
Set-up time	10 ms	10 ms	10 ms
Interpolation conversion time	_	<250 ns	<250 ns
Transition time	<10 µs	<10 µs	<100 ms

**Set-up time** is the time needed for the encoder readhead to start reading the position information after power-on (see diagram 1). **Interpolation conversion time** is the time needed for the encoder readhead to convert the position information into an output signal.

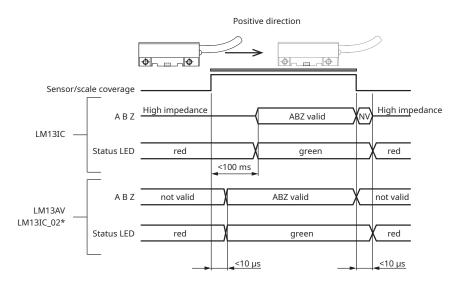
Transition time is the time it takes the encoder readhead to switch from an alarm state to a valid output signal (see diagram 2).

Diagram 1: Set-up time



<sup>\*</sup> In alarm state LED flashes red/green.

Diagram 2: Transition time



### **Status indicator LED**

After installation of the magnetic scale or ring (for MSD01, MR01D01 or MR02D02 data sheet refer to **RLS Media Center**), the readhead can be easily adjusted on the machine using the set-up LED indicator.

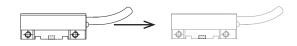
			Error output (s	pecial option 07)
LED Signa	al	Status	IC (E)	IC (E-)
•	Green	Good signal strength/set-up	U <sub>L</sub> ≤ 0.5 V	$U_{_{\rm H}} \ge 2.5~{\rm V}$
•	Red	<ul> <li>Poor signal strength. Possible reasons:</li> <li>Incorrect readhead orientation.</li> <li>Readhead installation out of tolerance.</li> <li>Demagnetisation of measuring scale.</li> <li>Insufficient power supply voltage.</li> </ul>	U <sub>H</sub> ≥ 2.5 V	$U_{_L}\!\leq 0.5~V$
•••	Red/green flashing	<ul> <li>IB, IC_02, IA_02: poor signal strength</li> <li>Poor signal strength. Possible reasons:</li> <li>Incorrect readhead orientation.</li> <li>Readhead installation out of tolerance.</li> <li>Demagnetisation of measuring scale.</li> <li>Insufficient power supply voltage.</li> </ul>	Not ap	olicable.

The LED signal functions listed in the table above do not indicate non-optimal installation of the readhead, such as accuracy outside the specified range or improper operation of the reference mark.

### Positive direction

Digital output signals – A leads B (magnetic scale is stationary)

Analogue output signals (1  $V_{pp}$ ) –  $V_1$  leads  $V_2$ 



For more information, see the MSD01, MR02D02 or MR01D01 data sheet at **RLS Media center**.



## **Output type**

### Analogue output signals (1 V<sub>np</sub>)

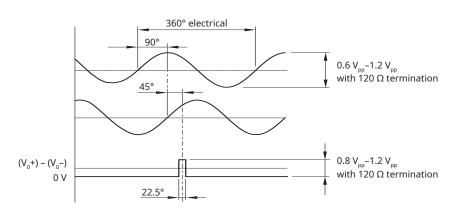
I M13A\

### **Specifications**

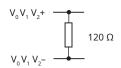
- 1.6	4744		
Power supply*	4.7 V to 7 V		
(voltage on readhead)	Reverse polarity protection		
Current consumption	<50 mA (without load)		
Voltage drop over cable	~13 mV/m (without load)		
	~54 mV/m (with 120 $\Omega$ load)		
Output signals	$V_1$ , $V_2$ , $V_0$		
Sine / cosine signals	Amplitude	$0.6  V_{pp}$ to $1.2  V_{pp}$	
	(with 120 $\Omega$ termination)		
	Phase shift	90° ± 0.5°	
Reference signal	Amplitude	$0.8  V_{pp}$ to $1.2  V_{pp}$	
	(with 120 $\Omega$ termination)		
	Position	45°	
	Width	22.5°	
Termination	$Z_0$ = 120 $\Omega$ between associated outputs		
Maximum cable length*	30 m		

<sup>\*</sup>Please consider voltage drop over cable.

### **Timing diagram**



### **Recommended signal termination**



### Incremental, RS422

LM13IC

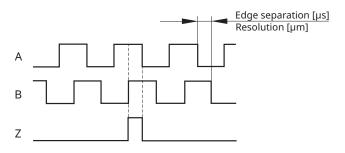
. •	- :::
tions	Specific
LIOH	Specific

Specifications	
Power supply*	4.7 V to 7 V
(voltage on readhead)	Reverse polarity protection
Current consumption	<35 mA (without load)
Voltage drop over cable	~13 mV/m (without load)
	~54 mV/m (with 120 $\Omega$ load)
Output signals	3 square-wave signals A, B, Z and their inverted signals A–, B–, Z–
Reference signal	1 or more square-wave pulse Z and its inverted pulse Z–
Signal level	Differential line driver according to EIA standard RS422:
	$U_{H} \ge 2.5 \text{ V at } -I_{H} = 20 \text{ mA}$
	$U_L \le 0.5 \text{ V}$ at $I_L = 20 \text{ mA}$
Permissible load	$Z_0 \ge 100~\Omega$ between associated outputs
	$I_L^{} \le 20$ mA max. load per output
	Capacitive load ≤ 1000 pF
	Outputs are protected against short circuit to 0 V and to +5 V
	Only one output shorted at a time
Alarm	High impedance on output lines A, B, A–, B–
	Special option 02: Alarm is not signaled by high impedance state of the A, B, /A, /B
	signals**
	Special option 07: Alarm signal is output parallel as line driver signal
Switching time – A, B, Z signals	t+, t- < 30 ns (with 1 m cable and recommended input circuit)
(10 to 90 %)	
Maximum cable length*	30 m
-	

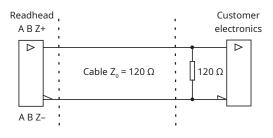
<sup>\*</sup> Please consider voltage drop over cable.

### **Timing diagram**

Complementary signals not shown



### **Recommended signal termination**



### Programming (for IC output only)

Readheads can be ordered preset to the required resolution or supplied so they can be programmed on the machine to the selected resolution. This programming is done by connecting the readhead to a computer via a programming interface **UPRG01**. The readhead must be ordered with the PRG option to use this function. For more information on the programming function of the LM13 readhead, see **UPRG01 Programming interface website**.

<sup>\*\*</sup> See diagram 1 and 2 on page 9



### Part numbering

2D0 00 **LM13** IC C Α 10 F **Output type** AV - Analogue voltage 1 V IC - Incremental, RS422 Interpolation factor (Resolution) AV: 000 - N/A IC: 13B - 8192 (0.244 µm) **09B** - 512 (3.906 µm) **D10** - 100 (20 µm) **12B** - 4096 (0.488 μm) **D50** - 500 **D08** - 80 (25 µm)  $(4 \mu m)$ **11B** - 2048 (0.977 μm) **D40** - 400 (5 µm) **06B** - 64 (31.250 µm) **2D0** - 2000 (1 μm) (6.250 µm) **D32** - 320 **D04** - 40  $(50 \mu m)$ **1D6** - 1600 (1.250 μm) **05B** - 32 (62.500 µm) **08B** - 256 (7.813 µm) **10B** - 1024 (1.953 μm) **04B** - 16 (125 µm) **D20** - 200 (10 µm) **1D0** - 1000 (2 μm) **03B** - 8 (250 µm) (12.500 µm) **D16** - 160 **D80** - 800 (2.500 μm) **07B** - 128 (15.625 µm) PRG - Programmable (preset to 1 µm) For DPI resolution see **Table of available resolutions**. Minimum edge separation IC: AV: **K** - 0.07 us (15 MHz) **E** - 4 us (0.25 MHz) **A** - N/A **A** - 0.12 µs (8 MHz) **F** - 5 µs (0.2 MHz) **G** - 10 µs (0.1 MHz)  ${f B}$  - 0.5  $\mu s$  (2 MHz) The customer's controller must support the **C** - 1 µs (1 MHz) **H** - 20 μs (0.05 MHz) selected edge separation time even if the **D** - 2 µs (0.5 MHz) encoder is used below the maximum speed. Reference mark A - With reference mark Magnetic scale or ring must be ordered with reference mark. If required, the cover foil can be installed over. **B** - Without reference mark sensor C - Without reference mark sensor but with periodic reference impulse as per scale pitch (every 2 mm) Reference periods correspond to pole length of magnetisation. Magnetic scale or ring must be ordered with no reference mark. Cable length 10 - 1.0 m (standard) (e.g. 13 - 1.3 m cable or 13 - 13 m cable if special option **0M** is chosen) Connector L - 15 pin D type plug A - 9 pin D type plug **F** - Flying lead, no connector H - 15 pin HD type plug D - 15 pin D type plug P - 9 pin D type plug **E** - 9 pin CPC connector **Special requirements** 

00 - No special requirements (standard)

02 - Shortened reaction time

**05** - 2.032 mm pitch

07 - Additional alarm output

**0M** - Cable length in meters

20 - High speed version (not available for all resolutions, please check MSD01 at RLS Media Center)

Not all part number combinations are valid. Please refer to the table of available combinations on the next page for options.

#### Table of available combinations

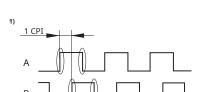
Series	Output type	Interpolation factor	Minimum edge separation	Reference mark	Cable length	Connector	Special requirements
LM13	IC	PRG**	А		10	A** / D / E / H / F	00 / 0M / 05 / 20
		xxx*	K/A/B/C/D/E/ F/G/H	A/B/C			00 / 0M / 02 / 05 / 07 / 20
		04B	A/B/C/D/E/F /G/H	В/С			
		03B	B/C/D/E/F/ G/H				
	AV	000	А	A/B/C		A/L/P/F	00 / 0M / 20 / 05

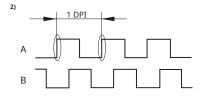
<sup>\*</sup> See chapter **Available resolutions** for available interpolation factors.

### Table of available resolutions

Resolution DPI (dots CPI (counts per inch per inch Part Interpolation In µm with 2.032 mm)<sup>1)</sup> 2.032 mm)<sup>2)</sup> factor 2 mm poles number 213 0.244140625 102,400 25,600 13B  $2^{12}$ 0.48828125 51,200 12,800 12B 211 0.9765625 11B 25,600 6,400 2D0 2000 1 25,000 6,250 1D6 1600 1.25 20,000 5,000 10B  $2^{10}$ 1.953125 12,800 3,200 1D0 1000 12,500 3,125 D80 800 2.5 10,000 2,500 09B 2<sup>9</sup> 3.90625 6,400 1,600 D50 500 6,250 1,562.5 **D40** 400 5 5,000 1,250 4,000 320 1,000 D32 6.25 28 08B 7.8125 3,200 800 200 10 2,500 625 D20 D16 160 12.5 2,000 500 07B  $2^7$ 15.625 1,600 400 D10 100 20 1,250 312.5 D08 80 25 1,000 250 06B 26 31.25 800 200 D04 40 50 500 125 05B 25 62.5 400 100 24 04B 125 200 50 03B **2**<sup>3</sup> 250 100 25

For the part numbering of the MS incremental magnetic scale or the MR radial and axial incremental magnetic ring, refer to the data sheets MSD01, MR02D02 and MR01D01 at RLS Media center.





<sup>\*\*</sup> Not available with special option 07.



### **Resolutions calculation**

#### For linear applications:

$$Resolution \, [\mu m] \, = \frac{Pole \, length \, [\mu m]}{Interpolation \, factor} = \frac{2000}{Interpolation \, factor}$$

#### For ring applications:

Resolution [CPR] = Pole number\* × Interpolation factor

CPR - Counts per revolution (resolution)

PPR - Pulses per revolution

Resolution [PPR] = 
$$\frac{\text{Resolution [CPR]}}{4}$$

\* See pole numbers in the MR01D01 or MR02D02 data sheet at **RLS Media center.** 

#### Resolutions calculation for CPI/DPI

$$Resolution \, [\mu m] \, = \frac{Pole \, length \, [\mu m]}{Interpolation \, factor} = \frac{2032}{Interpolation \, factor}$$

Resolution [CPI] = 
$$\frac{\text{Inch [}\mu\text{m}]}{\text{Resolution [}\mu\text{m}]}$$
 = 
$$= \frac{\text{Inch [}\mu\text{m}] \times \text{Interpolation factor}}{\text{Pole length [}\mu\text{m}]} = \frac{25400 \times \text{Interpolation factor}}{2032}$$

Resolution [DPI] = 
$$\frac{CPI}{4}$$

### **Accessories**





USB encoder interface **E201-9Q** 

Compatible with LM13IC only



Programmable interface **UPRG01** 

Compatible with LM13IC only



### **Head office**

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Visit our website to contact your nearest sales representative.

#### **Document issues**

Issue	Date	Page	Description
6	3. 10. 2022	General	New design, data amended
7	12.1. 2023	13, 14	Resolutions amended

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